Electronic Journal of Differential Equations, Vol. 2006(2006), No. 155, pp. 1–9. ISSN: 1072-6691. URL: http://ejde.math.txstate.edu or http://ejde.math.unt.edu ftp ejde.math.txstate.edu (login: ftp)

SOLVING *p*-LAPLACIAN EQUATIONS ON COMPLETE MANIFOLDS

MOHAMMED BENALILI, YOUSSEF MALIKI

ABSTRACT. Using a reduced version of the sub and super-solutions method, we prove that the equation $\Delta_p u + k u^{p^*-1} - K u^{p^*-1} = 0$ has a positive solution on a complete Riemannian manifold for appropriate functions $k, K : M \to \mathbb{R}$.

1. INTRODUCTION

Let (M, g) be an *n*-dimensional complete and connected Riemannian manifold $(n \ge 3)$ and let $p \in (1, n)$. We are interested in the existence of positive solutions $u \in H^p_{1 \text{ loc}}(M)$ (the standard Sobolev space of order p) of the equation

$$\Delta_p u + k u^{p-1} - K u^{p^* - 1} = 0 \tag{1.1}$$

with $p^* = \frac{pn}{n-p}$ and $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2}\nabla u)$ is the *p*-Laplacian of u. As usual $u \in H^p_{1,\operatorname{loc}}(M)$ is defined to be a weak solution of (1.1) if

$$\int_{M} -|\nabla u|^{p-2} \nabla u \nabla v + (k u^{p-1} - K u^{p^*-1})v = 0$$
(1.2)

for each $v \in C_0^{\infty}(M)$. A supersolution (respectively a subsolution) $u \in H_{1,\text{loc}}^p(M)$ is defined in the same way by changing = by \leq (respect \geq) in equation(1.2) and requiring that the test function $v \in C_0^{\infty}(M)$ to be non negative. Throughout this paper, we will assume that k and K are smooth real valued functions on M. Following the terminology in [3], this equation is referred to as the generalized scalar curvature type equation, it's an extension of the equation of prescribed scalar curvature. In the case of a compact manifold, the problem was considered in [3]. One of the results obtained in this latter paper is the following theorem

Theorem 1.1. Let (M, g) be a compact Riemannian manifold with $n \ge 2$ and let $p \in (1, n)$. Let k and K be smooth real functions on M. If we assume that k and K are both positive, then (1.1) possesses a positive solution $u \in C^{1,\alpha}(M)$.

In this paper, we look for positive solutions of (1.1) on complete Riemannian manifolds. To achieve this task, we use a recent result obtained by the authors in [2]. Before quoting this result we recall some definitions. A nonnegative and smooth function K on a complete manifold is said *essentially positive* if there exists an

²⁰⁰⁰ Mathematics Subject Classification. 31C45, 53C21.

Key words and phrases. Differential geometry; nonlinear partial differential equations.

^{©2006} Texas State University - San Marcos.

Submitted June 28, 2005. Published December 14, 2006.

exhaustion by compact domains $\{\Omega_i\}_{i\geq 0}$ such that $M = \bigcup_{i\geq 0}\Omega_i$ and $K|_{\partial\Omega_j} > 0$ for any $j\geq 0$. Moreover, if there is a positive supersolution $u\in H_1^p(\Omega_i)\cap C^0(\Omega_i)$ on each Ω_i of (1.1) the essentially positive function K is said to be *permissible*. With this terminology the following theorem has been established in [2]

Theorem 1.2. Let (M,g) be a complete non compact Riemannian manifold of dimension $n \ge 3$ and k, K be smooth real valued functions on M. Suppose that Kis permissible and $k \le K$. If there exists a positive subsolution $u_- \in H^p_{1,\text{loc}}(M) \cap$ $L^{\infty}(M) \cap C^0(M)$ of (1.1) on M, then (1.1) has a positive and maximal weak solution $u \in H^p_1(M)$. Moreover $u \in C^{1,\alpha}(\Omega_i)$ on each compact Ω_i for some $\alpha \in (0, 1)$.

The Riemannian manifold M will be said of bounded geometry if the Ricci curvature of M is bounded from below and the injectivity radius is strictly positive everywhere.

We formulate our main result as follows:

Theorem 1.3. Let (M,g) be a complete non compact Riemannian manifold of dimension $n \ge 3$ and k, K be smooth real valued functions on M. Suppose that

- (a) the function K is permissible and $K \ge c_o > 0$ where c_o is a real constant, k is bounded and satisfies $k \le K$, and $\int_{\Omega_i} k = 0$, on each compact domain Ω_i of the exhaustion of M.
- (b) M is of bounded geometry.

Then (1.1) has a weak positive maximal solution $u \in H_1^p(M)$. Moreover $u \in C_{loc}^{1,\alpha}(M)$ for some $\alpha \in (0,1)$.

Our paper is organized as follows: In the first section we construct a supersolution of (1.1) on each compact subset of M. In the second section, we show the existence of a positive eigenfunction of the nonlinear operator $L_p u = -\Delta_p u - k u^{p-1}$ on M which we will use next to construct a global subsolution of our equation.

First, we establish the following result.

Lemma 1.4. Let Ω be a compact domain of M and f be a C^{∞} function on Ω . The equation

$$\begin{aligned} -\Delta_p \phi &= f \quad in \ \Omega - \partial \Omega \\ \phi &= 0 \quad on \ \partial \Omega \end{aligned} \tag{1.3}$$

admits a solution $\phi \in C^{1,\alpha}(\Omega)$.

Proof. Letting $A = \{\phi \in H^p_{1,0}(\Omega) : \int_{\Omega} f\phi = 1\}$, we put

$$\mu = \inf_{\phi \in K} \int_{\Omega} |\nabla \phi|^p.$$

The set A is non empty since it contains the function $\phi = \frac{\operatorname{sgn}(f)|f|^{p-1}}{\int_{\Omega} |f|^p}$.

Let $(\phi_i)_{i \in \mathbb{N}}$ be a minimizing sequence in A, that is,

$$\lim_{i \to \infty} \int_{\Omega} |\nabla \phi_i|^p = \mu$$

Then, if $\lambda_{1,p}$ denotes the first nonvanishing eigenvalue of the *p*-Laplacian operator, we have

$$\lambda_{1,p} \le \frac{\int_{\Omega} |\nabla \phi_i|^p}{\int_{\Omega} |\phi_i|^p}$$

 $\mathrm{EJDE}\text{-}2006/155$

 \mathbf{SO}

$$\int_{\Omega} |\phi_i|^p \le \lambda_{1,p}^{-1} \int_{\Omega} |\nabla \phi_i|^p < \frac{\mu}{\lambda_{1,p}} + 1.$$

The sequence $(\phi_i)_{i \in \mathbb{N}}$ is bounded in $H_1^p(\Omega)$, hence by the reflexivity of the space $H_1^p(\Omega)$ and the Rellich-Kondrakov theorem, there exists a subsequence of $(\phi_i)_{i \in \mathbb{N}}$ still denoted (ϕ_i) such that

- (a) $(\phi_i)_{i \in \mathbb{N}}$ converges weakly to $\phi \in H_1^p(\Omega)$
- (b) $(\phi_i)_{i \in \mathbb{N}}$ converges strongly to $\phi \in L^p(\Omega)$.
- From (b) we deduce that $\phi_i \longrightarrow \phi$ in $L^1(\Omega)$ then $\phi \in A$ and from (a) we get

$$\|\phi\|_{H^p_1(\Omega)} \le \lim_{i \to +\infty} \inf \|\phi_i\|_{H^p_1(\Omega)}.$$

Taking into account of (b) again, we obtain

$$\int_{\Omega} |\nabla \phi|^p \le \liminf_{i \to +\infty} \int_{\Omega} |\nabla \phi_i|^p = \mu.$$

Since $\phi \in A$, we get

$$\int_{\Omega} |\nabla \phi|^p = \mu = \inf_{\psi \in K} \int_{\Omega} |\nabla \psi|^p.$$

The Lagrange multiplier theorem allows us to say that ϕ is a weak solution of (1.3).

The regularity of ϕ follows from the next proposition, with the following notation

$$W^{1,p}(\Omega) = \begin{cases} H_1^p(\Omega) & \text{if } \partial \Omega = \phi \\ H_{1,0}^p(\Omega) & \text{if } \partial \Omega \neq \phi \,. \end{cases}$$

Proposition 1. Let $h \in C^{\circ}(\Omega \times R)$ be such that, for any $(x, r) \in \Omega \times R$, $|h(x, r)| \leq C|r|^{p^*-1} + D$.

If $u \in W^{1,p}(\Omega)$ is a solution of $-\Delta_p u + h(x, u) = 0$, then $u \in C^{1,\alpha}(\Omega)$.

The above proposition was proved in ([3]), in the context of compact Riemannian manifolds without boundary. The proof is in its essence based on the Sobolev inequality and since this latter is also valid in $\mathring{H}_1^p(\Omega)$ as in $H_1^p(\Omega)$, it follows that proposition (1) remains true in the case of compact Riemannian manifolds with boundary.

2. EXISTENCE OF A SUPERSOLUTION

In this section we construct a positive supersolution of (1.1) on each compact domain of M.

Theorem 2.1. Let Ω be a compact domain of M. If K is a smooth function such that $K \geq c_0 > 0$ and k is a smooth function with $k \leq K$, then there exists a positive supersolution of (1.1) in Ω .

Proof. Letting $u = e^v$ where $v \in H_1^p(\Omega)$ is a function which will be precise later and $q = p^* - 1$, then we get for every $\phi \in H_1^p(\Omega)$ with $\phi \ge 0$

$$\int_{\Omega} \Delta_p u\phi = \int_{\Omega} e^{(p-1)v} (\Delta_p v + (p-1)|\nabla v|^p)\phi$$

and

$$\int_{\Omega} (\Delta_p u + k u^{p-1} - K u^q) \phi = \int_{\Omega} e^{(p-1)v} (\Delta_p v + (p-1) |\nabla v|^p + k - K e^{(q-p+1)v}) \phi.$$

So it suffices to show the existence of v such that

$$\int_{\Omega} e^{(p-1)v} (\Delta_p v + (p-1)|\nabla v|^p + k - K e^{(q-p+1)v}) . \phi \le 0$$
(2.1)

Let b > 0 be a constant and consider the solution of $\Delta_p h = -b^{1-p}k$ which is guaranteed by Lemma 1.4.

Now putting v = bh + t where t is a real constant to be chosen later. The inequality (2.1) becomes

$$\int_{\Omega} e^{(p-1)(bh+t)} (b^{p-1}\Delta_p h + (p-1)b^p |\nabla h|^p + k - Ke^{(q-p+1)(bh+t)})\phi \le 0$$

If we choose t such that $e^{(q-p+1)t} = b^{p-1}$, we will find that

$$\int_{\Omega} e^{(p-1)(bh+t)} ((p-1)b|\nabla h|^p - Ke^{(q-p+1)bh})\phi$$

$$\leq \int_{\Omega} e^{(p-1)(bh+t)} ((p-1)b|\nabla h|^p - Km_o)\phi \leq 0$$

where $m_o = \min_{x \in \Omega} e^{(q-p+1)bh(x)}$ and since the function $K \ge c_o > 0$, we choose b small enough so that

$$|\nabla h|^p \le \frac{c_o m_o}{b(p-1)}$$

we get the desired result.

3. EXISTENCE OF A SUBSOLUTION

The operator $L_p u = -\Delta_p u - k u^{p-1}$ under Dirichlet conditions has a first eigenvalue $\lambda_{1,p}^{\Omega}$ on each open and bounded domain $\Omega \subset M$ which is variationally defined as

$$\lambda_{1,p}^{\Omega} = \inf\left(\int_{\Omega} |\nabla \phi|^p - k |\phi|^p\right) \tag{3.1}$$

where the infimum is extended to the set

$$A = \{ \phi \in H^p_{1,0}(\Omega) : \int_{\Omega} |\phi|^p = 1 \}.$$

Since $|\nabla \phi| = |\nabla |\phi||$, we can assume that $\phi \ge 0$. The corresponding positive eigenfunction is solution of the Dirichlet problem

$$\Delta_p \phi + k \phi^{p-1} = -\lambda_{1,p}^{\Omega} \phi^{p-1} \quad \text{in } \Omega$$

$$\phi > 0 \quad \text{in } \Omega$$

$$\phi = 0 \quad \text{on } \partial \Omega$$

(3.2)

Let $\{\Omega_i\}_{i\geq 0}$ be an exhaustion of M by compact domains with smooth boundary such that $\Omega_i \subset \mathring{\Omega}_{i+1}$

Lemma 3.1. If k is bounded function, then the sequence $\lambda_{1,p}^{\Omega_i}$ defined by (3.1) converges.

EJDE-2006/155

Proof. By definition, $\lambda_{1,p}^{\Omega_i}$ is a decreasing sequence. Let $\lambda_{1,p}$ its limit, since the function k is bounded, there exists a constant c > 0 such that $-k + c \ge 1$, then

$$\int_{\Omega} |\nabla \phi|^p + (c-k)\phi^p \ge \int_{\Omega} |\nabla \phi|^p + \phi^p$$
$$\ge 2^{1-p} \left(\left(\int_{\Omega} |\nabla \phi|^p \right)^{1/p} + \left(\int_{\Omega} \phi^p \right)^{1/p} \right)^p$$
$$= 2^{1-p} \|\phi\|_{H^p(\Omega)}^p$$

so the operator $L_p u = -\Delta_p u + (c-k)u^{p-1}$ is coercive and we have, for ϕ_i any eigenfunction corresponding to $\lambda_{1,p}^{\Omega_i}$,

$$\begin{split} \lambda_{1,p}^{\Omega_{i}} &= \int_{\Omega_{i}} |\nabla \phi_{i}|^{p} - k \phi_{i}^{p} \\ &\geq -c + 2^{1-p} \|\phi_{i}\|_{H_{1}^{p}(\Omega)}^{p} \\ &\geq -c + 2^{1-p} \geq -c + 2^{1-n} \,. \end{split}$$

Then $\lambda_{1,p} > -\infty$.

Lemma 3.2. If k is bounded, then the eigenfunction problem

$$\Delta_p \phi + k \phi^{p-1} = -\lambda_{1,p} \phi^{p-1} \quad in \ M$$

$$\phi > 0 \quad in \ M$$
(3.3)

has a positive solution $\phi \in C^{1,\alpha}_{loc}(M)$.

Proof. Letting $(\Omega_i)_{i>1}$ be an exhaustive covering of the complete manifold M by compact subsets and (ϕ_i) be the sequence of the first nonvanishing eigenfonctions (positive) of the operator $L_p u = -\Delta_p u - k u^{p-1}$ on each Ω_i . Multiplying (3.3) by ϕ_i and integrating over Ω_i , we get

$$\int_{\Omega_i} |\nabla \phi_i|^p - k \phi_i^p = \lambda_{1,p}^{\Omega_i} \int_{\Omega_i} \phi_i^p = \lambda_{1,p}^{\Omega_i} \le \lambda_{1,p}^{\Omega_i}$$

so that

$$\int_{\Omega_i} |\nabla \phi_i|^p \le \max_{x \in M} |k| + \lambda_{1,p}^{\Omega_1} < \infty.$$

On the other hand,

$$\left(\left(\int_{\Omega_{i}} |\nabla\phi_{i}|^{p}\right)^{1/p} + \left(\int_{\Omega_{i}} \phi_{i}^{p}\right)^{1/p}\right)^{p} \leq 2^{p-1} \left(\int_{\Omega_{i}} |\nabla\phi_{i}|^{p} + \phi_{i}^{p}\right)$$

$$\leq 2^{p-1} \left(1 + \max_{x \in M} |k| + \lambda_{1,p}^{\Omega_{1}}\right) < \infty$$
(3.4)

and by the reflexivity of the space $H_1^p(M)$, we deduce that

 $\phi_i \to \phi$ weakly in $H_1^p(M)$

and

$$\|\phi\|_{H^{p}(M)}^{p} \le \liminf \|\phi_{i}\|_{H^{p}(M)}^{p}.$$
(3.5)

 $\|\phi\|_{H_{1}^{p}(M)}^{p} \leq \liminf \|\phi_{i}\|_{H_{1}^{p}(M)}^{p}.$ (3.5) Now since $\int_{M} \phi_{i}^{p} = 1$, for every $\varepsilon > 0$ there exists a compact domain $K_{i} \subset M$ such that $\int_{M \setminus K_{i}} \phi_{i}^{p} < \frac{\varepsilon}{2^{i}}$, let $K = \bigcap_{i=1}^{\infty} K_{i}$ and

$$\int_{M\setminus K} \phi_i^p = \int_{\bigcup_{i=1}^\infty (M\setminus K_i)} \phi_i^p \le \sum_{i=1}^\infty \int_{M\setminus K_i} \phi_i^p < \epsilon.$$

From (3.4) we obtain by Rellich-Kondrakov theorem that

$$\phi_i \to \phi$$
 strongly in $L^p(K)$.

We claim that

$$\int_{M} \phi^{p} = 1; \tag{3.6}$$

since, if it is not the case we have by (3.5)

$$1 - \int_M \phi^p > 0,$$

consequently

$$1 = \lim_{i \to \infty} \int_M \phi_i^p \le \varepsilon + \lim_{i \to \infty} \int_K \phi_i^p = \varepsilon + \int_K \phi^p$$

and hence $\varepsilon \ge 1 - \int_M \phi^p$. A contradiction with the fact that ε is arbitrary fixed. Now from (3.5) and (3.6) we get

$$\int_{M} |\nabla \phi|^{p} \leq \liminf \int_{M} |\nabla \phi_{i}|^{p}$$

hence

$$\int_{M} |\nabla \phi|^{p} - k\phi^{p} \le \liminf \left(\int_{M} |\nabla \phi_{i}|^{p} - k\phi_{i}^{p} \right)$$

which by lemma 3.1 goes to $\lambda_{1,p}$, and since $\int_M \phi^p = 1$, we obtain

$$\int_M |\nabla \phi|^p - k\phi^p = \lambda_{1,p}$$

So ϕ is a weak solution of the equation

$$\Delta_p \phi + k \phi^{p-1} = -\lambda_{1,p} \phi^{p-1}$$

From proposition 1, we deduce that $\phi \in C^{1,\alpha}_{loc}(M)$. It remains to show that ϕ is positive, which is deduced from the next proposition.

Proposition 2 (Druet [3]). Let (Ω, g) be a compact Riemannian n-manifold $n \geq 2$, $1 . Let <math>u \in C^1(\Omega)$ be such that $-\Delta_p u + h(x, u) \ge 0$ on Ω , h fulfilling the conditions

$$\begin{split} h(x,r) < h(x,s), \quad x \in \Omega, \; 0 \leq r < s \\ |h(x,u)| \leq C(K+|r|^{p-2})|r|, \quad (x,r) \in M \times R, \; C > 0 \end{split}$$

If $u \geq 0$ on Ω and u does not vanish identically, then u > 0 on Ω .

If λ is an eigenvalue of the operator

$$L_p u = -\Delta_p \phi - k |\phi|^{p-2} \phi,$$

so is $\lambda + c$ for the operator

$$L_c u = -\Delta_p \phi - (k - c) |\phi|^{p-2} \phi$$

where c is a constant and since k is bounded function we choose c such that c-k > 0, and then we get

$$-\Delta_p \phi + h(x,\phi) \ge 0$$

where

$$h(x,\phi) = (c - k(x))\phi^{p-1}.$$

EJDE-2006/155

Obviously the function h satisfies the assumptions of proposition 2 and we have $\phi > 0$.

Now we establish the following lemma which will be used later.

Lemma 3.3. Let M be a Riemannian manifold of bounded geometry. Suppose that a(x) is a bounded smooth function on M and $u \in H_1^p(M)$ be a weak solution of the equation

$$\Delta_p u + a(x)u^{p-1} = 0 (3.7)$$

then $u \in L^{\infty}(M)$.

Proof. We are going to use Moser's iteration scheme. Let $k \ge 1$ be any real and t = k + p - 1. Multiplying (3.7) by u^k (k > 1) and integrating over M, we get

$$-k\int_{M} |\nabla u|^{p} u^{k-1} + \int_{M} a(x)u^{p+k-1} = 0.$$
(3.8)

Using Sobolev's inequality, we get for any fixed $\varepsilon>0$

$$\begin{aligned} \|u^{\frac{t}{p}}\|_{p^{*}}^{p} &= \|u\|_{t\frac{p^{*}}{p}}^{t} \\ &\leq (K(n,p)^{p} + \varepsilon)\|\nabla u^{\frac{t}{p}}\|_{p}^{p} + B\|u\|_{t}^{t} \\ &= (K(n,p)^{p} + \varepsilon)(\frac{t}{p})^{p}\|u^{\frac{t}{p}-1}\nabla u\|_{p}^{p} + B\|u\|_{t}^{t} \end{aligned} (3.9)$$

where K(n, p) is the best constant in the Sobolev's embedding $H_1^p(\mathbb{R}^n) \subset L^{p*}(\mathbb{R}^n)$ (see Aubin [1] or Talenti [4]) and B a positive constant depending on ϵ ; since

$$\|u^{\frac{t}{p}-1}\nabla u\|_p^p = \int u^{t-p} |\nabla u|^p$$

and taking account of (3.8) we get

$$\int u^k \Delta_p u = -k \int u^{k-1} |\nabla u|^p \le ||a||_{\infty} ||u||_t^t.$$

Then (3.9) becomes

$$\|u\|_{t\frac{p^{*}}{p}}^{t} \leq (K(n,p)^{p} + \varepsilon)(\frac{t}{p})^{p}\frac{1}{k}(\|a\|_{\infty} + B)\|u\|_{t}^{t}$$

so that

$$\|u\|_{t\frac{p^{*}}{p}} \leq \left((K(n,p)^{p} + \varepsilon) \left(\frac{t}{p}\right)^{p} \frac{1}{k} (\|a\|_{\infty} + B) \right)^{\frac{1}{t}} \|u\|_{t}.$$
(3.10)

Putting

$$\frac{t}{p}=\beta^i$$

where *i* is a positive integer and $\beta = \frac{p^*}{p} = \frac{n}{n-p}$, (3.10) becomes

$$\|u\|_{p\beta^{i+1}} \le \left((K(n,p)^p + \varepsilon)\beta^{pi} (\|a\|_{\infty} + B) \right)^{\frac{1}{p\beta^i}} \|u\|_{p\beta^i} .$$
(3.11)

Recurrently, we obtain

 $\|u\|_{p\beta^{i+1}} \le (K(n,p)^p + \varepsilon)^{\frac{1}{p}(\sum_{j=0}^i \frac{1}{\beta^j})} \beta^{\sum_{j=0}^i \frac{j}{\beta^j}} (\|a\|_{\infty} + B)^{\frac{1}{p}(\sum_{j=0}^i \frac{1}{\beta^j})} \|u\|_p.$ (3.12) Now, since

$$\sum_{j=0}^{\infty} \frac{1}{\beta^j} = \frac{\beta}{\beta - 1} = \frac{n}{p}$$

and

$$\begin{split} \sum_{j=0}^{\infty} \frac{j}{\beta^{j}} &= \sum_{j=1}^{\infty} \frac{j}{(1+\pi)^{j}} \\ &\leq \sum_{j=1}^{\infty} \frac{j}{\sum_{p=0}^{j} C_{j}^{p} \pi^{p}} = \sum_{j=1}^{\infty} \frac{1}{\pi \sum_{p=0}^{j-1} C_{j}^{p} \pi^{p}} \\ &= \frac{1}{\pi} \sum_{j=1}^{\infty} \frac{1}{(1+\pi)^{j-1}} = \frac{1}{\pi} \sum_{j=0}^{\infty} \frac{1}{(1+\pi)^{j}} \\ &= \frac{n-p}{p} \sum_{j=0}^{\infty} \frac{1}{\beta^{j}} = \frac{n(n-p)}{p^{2}}, \end{split}$$

it follows by letting $j \to \infty$ in (3.12) that $u \in L^{\infty}(M)$.

Theorem 3.4. Let (M, g) be a complete noncompact Riemannian manifold of dimension $n \geq 3$ with bounded geometry. Suppose that $k \in C^{\infty}(M) \cap L^{\infty}(M)$; then there exists a positive subsolution of the equation $\Delta_p u + ku^{p-1} - Ku^{p^*-1} = 0$ on M.

Proof. Since $k \in L^{\infty}(M)$, there exists a positive constant c > 0 such that the operator $L_c u = -\Delta_p \phi + (c-k)\phi^{p-1}$ is coercive, so by lemma 3.2 its first non vanishing eigenvalue $\lambda_{1,p} + c > 0$. If ϕ denotes the corresponding positive eigenfunction to $\lambda_{1,p}$, by lemma 3.3 we may assume that $\phi < 1$.

For r > 0 we consider

$$u_{-} = \left(e^{r^{2}} - \phi^{r^{3}}\right)^{\frac{1}{r}+1}$$

and by a direct computations we obtain in the sense of distribution

$$\nabla u_{-} = -r^{2}(r+1)(e^{r^{2}} - \phi^{r^{3})^{\frac{1}{r}}}\phi^{r^{3}-1}\nabla\phi,$$

$$\Delta_{p}u_{-} = \left[r^{2}(r+1)(e^{r^{2}} - \phi^{r^{3})^{1/r}}\phi^{r^{3}-1}\right]^{p-1}$$

$$\times \left[-\Delta_{p}\phi + (p-1)\left(\frac{1-r^{3}}{\phi} + \frac{r^{2}\phi^{r^{3}-1}}{e^{r^{2}} - \phi^{r^{3}}}\right)|\nabla\phi|^{p}\right].$$

Hence

$$\begin{split} &\Delta_{p}u_{-} + ku_{-}^{p-1} - Ku_{-}^{q} \\ &= \left[r^{2}(r+1)(e^{r^{2}} - \phi^{r^{3}})^{\frac{1}{r}}\phi^{r^{3}}\right]^{p-1} \\ &\times \left[-\Delta_{p}\phi + (p-1)\left(\frac{1-r^{3}}{\phi} + \frac{r^{2}\phi^{r^{3}-1}}{e^{r^{2}} - \phi^{r^{3}}}\right)|\nabla\phi|^{p} + k\left(\frac{e^{r^{2}} - \phi^{r^{3}}}{r^{2}(r+1)\phi^{r^{3}}}\right)^{p-1}\phi^{p-1} \\ &- K\left(\frac{e^{r^{2}} - \phi^{r^{3}}}{r^{2}(r+1)\phi^{r^{3}}}\right)^{p-1}(e^{r^{2}} - \phi^{r^{3}})^{(q-p+1)(1+\frac{1}{r})}\phi^{p-1}\right] \\ &= \left[r^{2}(r+1)(e^{r^{2}} - \phi^{r^{3}})^{\frac{1}{r}}\phi^{r^{3}-1}\right]^{p-1} \\ &\times \left[\lambda_{1,p} + (p-1)\frac{1}{\phi^{p}}\left(1 - r^{3} + \frac{r^{2}\phi^{r^{3}}}{e^{r^{2}} - \phi^{r^{3}}}\right)|\nabla\phi|^{p} + k\left(\left(\frac{e^{r^{2}} - \phi^{r^{3}}}{r^{2}(r+1)\phi^{r^{3}}}\right)^{p-1} + 1\right) \\ &- K\left(\frac{e^{r^{2}} - \phi^{r^{3}}}{r^{2}(r+1)\phi^{r^{3}}}\right)^{p-1}(e^{r^{2}} - \phi^{r^{3}})^{(q-p+1)(1+\frac{1}{r})}\right]. \end{split}$$

EJDE-2006/155

Now since

$$\lim_{r \to 0} (e^{r^2} - \phi^{r^3})^{1 + \frac{1}{r}} = 0$$

and

$$\lim_{r \to 0} \frac{r^2}{e^{r^2} - \phi^{r^3}} = 1 \,,$$

we deduce that

$$u_{-} = (e^{r^{2}} - \phi^{r^{3}})^{1 + \frac{1}{r}} \in H^{p}_{1, \text{loc}}(M)$$

is a subsolution of (1.1) and clearly $u_{-} \in C^{o}(M) \cap L^{\infty}(M)$. The main theorem (Theorem 1.3) is a consequence of theorem 2.1 and theorem 3.4.

References

- Aubin.T, problèmes isopérimétriques et espaces de Sobolev. J. Diff. Géom 11 (1976), 573-598.
 M. Benalili, Y Maliki, Reduction method for proving the existence of solutions to elliptic
- equations involving the p-Laplacian. Electr.Journal of Differential Equations 106 (2003) 10pp.
 [3] O. Druet, Generalized scalar curvature type equations on compact Riemannian manifolds. Proc. Roy. Soc. Edinburgh Sect. A130 (2000) No 4, 767-788.
- [4] E. Hebey, Introduction à l'analyse non linéaire sur les variétés. Ed. Diderot (1997).

Mohammed Benalili, Université Abou -Bekr Belkaïd, Faculté des sciences, Départ. Mthématiques, B.P. 119, Tlemcen, Algerie

 $E\text{-}mail\ address:\ \texttt{m_benaliliQmail.univ-tlemcen.dz}$

Youssef Maliki, Université Abou -Bekr Belkaïd, Faculté des sciences, Départ. Mthématiques, B.P. 119, Tlemcen, Algerie

E-mail address: malyouc@yahoo.fr