

ANTI-PERIODIC SOLUTIONS FOR SECOND ORDER DIFFERENTIAL INCLUSIONS

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ABSTRACT. In this paper, we extend the existence results presented in [9] for L^p spaces to operator inclusions of Hammerstein type in $W^{1,p}$ spaces. We also show an application of our results to anti-periodic boundary-value problems of second-order differential equations with nonlinearities depending on u' .

1. INTRODUCTION

This paper concerns the second-order boundary-value problem

$$\begin{aligned} -u''(t) &\in Au(t) + f(t, u(t), u'(t)) \quad \text{for a.e. } t \in [0, T] \\ u(0) &= -u(T), \quad u'(0) = -u'(T), \end{aligned}$$

where $0 < T < \infty$, A is an m -dissipative multivalued mapping in a Hilbert space E and $f : [0, T] \times E^2 \rightarrow 2^E$. However, in this section, and in Section 2, we shall assume generally that E is a Banach space.

A function $u \in C^1([0, T]; E)$ is said to be T -anti-periodic if $u(0) = -u(T)$ and $u'(0) = -u'(T)$. Note that there exists a close connection between the anti-periodic problem and the periodic one. Indeed, if $u \in W^{2,p}(0, T; E)$ ($1 \leq p < \infty$) is a T -anti-periodic solution of the inclusion

$$-u''(t) \in Au(t) + f(t, u(t), u'(t)) \quad \text{a.e. on } [0, T]$$

and A, f are odd in the following sense:

$$A(-x) = -Ax \quad \text{and} \quad f(t, -x, -y) = -f(t, x, y),$$

then the function

$$\tilde{u}(t) = \begin{cases} u(t), & 0 \leq t \leq T \\ -u(t - T), & T < t \leq 2T \end{cases}$$

belongs to $W^{2,p}(0, 2T; E)$, is $2T$ -periodic, i.e., $\tilde{u}(0) = \tilde{u}(2T)$, $\tilde{u}'(0) = \tilde{u}'(2T)$, and solves the inclusion

$$-\tilde{u}''(t) \in A\tilde{u}(t) + \tilde{f}(t, \tilde{u}(t), \tilde{u}'(t)) \quad \text{a.e. on } [0, 2T]$$

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where

$$\tilde{f}(t, x, y) = \begin{cases} f(t, x, y), & 0 \leq t \leq T \\ f(t - T, x, y), & T < t \leq 2T. \end{cases}$$

The anti-periodic boundary value problem for various classes of evolution equations has been considered by Aftabizadeh-Aizicovici-Pavel [1], [2]; Aizicovici-Pavel [3], Aizicovici-Pavel-Vrabie [4], Cai-Pavel [6], Coron [7], Haraux [17] and Okochi [19, 20].

Let us denote by $|\cdot|$ the norm of E , by $|\cdot|_p$ the usual norm of $L^p(0, T; E)$ and by $|\cdot|_{1,p}$ the norm of $W^{1,p}(0, T; E)$, $|u|_{1,p} = \max\{|u|_p, |u'|_p\}$. One of the reasons of working with anti-periodic solutions is given by the following proposition.

Proposition 1.1. *If $u \in W^{1,p}(0, T; E)$ ($1 \leq p \leq \infty$) and $u(0) = -u(T)$, then*

$$|u(t)| \leq \frac{1}{2} T^{\frac{p-1}{p}} |u'|_p, \quad t \in [0, T]. \quad (1.1)$$

Proof. Adding $u(t) = u(0) + \int_0^t u'(s)ds$ and $u(t) = u(T) - \int_t^T u'(s)ds$ we have

$$2u(t) = \int_0^t u'(s)ds - \int_t^T u'(s)ds.$$

Hence

$$2|u(t)| \leq \int_0^t |u'(s)|ds + \int_t^T |u'(s)|ds = \int_0^T |u'(s)|ds.$$

Now Hölder's inequality gives (1.1). \square

Let us denote

$$C_a^1 = \{u \in C^1([0, T]; E) : u \text{ is } T\text{-anti-periodic}\}.$$

In what follows for a subset $K \subset E$, by $P_a(K)$ and $P_{kc}(K)$ we shall denote the family of all nonempty acyclic subsets of K and, respectively, the family of all nonempty compact convex subsets of K .

Recall that a metric space Ξ is said to be *acyclic* if it has the same homology as a single point space, and that Ξ is called an *absolute neighborhood retract* (ANR for short) if for every metric space Z and closed set $A \subset Z$, every continuous map $f : A \rightarrow \Xi$ has a continuous extension \hat{f} to some neighborhood of A . Note that every compact convex subset of a normed space is an ANR and is acyclic.

Our main abstract tools are: The Eilenberg-Montgomery fixed point theorem [13, 18]; a lemma of Petryshyn-Fitzpatrick [14]; and strong and weak compactness criteria in $L^p(0, T; E)$ (see [16] and [12]), where E is a general (non-reflexive) Banach space.

Theorem 1.2. *Let Ξ be acyclic and absolute neighborhood retract, Θ be a compact metric space, $\Phi : \Xi \rightarrow P_a(\Theta)$ be an upper semicontinuous map and $\Gamma : \Theta \rightarrow \Xi$ be a continuous single-valued map. Then the map $\Gamma\Phi : \Xi \rightarrow 2^\Xi$ has a fixed point.*

Lemma 1.3. *Let X be a Fréchet space, $D \subset X$ be closed convex and $N : D \rightarrow 2^X$. Then for each $\Omega \subset D$ there exists a closed convex set K , depending on N , D and Ω , with $\Omega \subset K$ and $\overline{\text{conv}}(\Omega \cup N(D \cap K)) = K$.*

Theorem 1.4. *Let $p \in [1, \infty]$. Let $M \subset L^p(0, T; E)$ be countable and suppose that there exists a $\nu \in L^p(0, T)$ with $|u(t)| \leq \nu(t)$ a.e. on $[0, T]$ for all $u \in M$. Assume $M \subset C([0, T]; E)$ if $p = \infty$. Then M is relatively compact in $L^p(0, T; E)$ if and only if*

- (i) $\sup_{u \in M} |\tau_h u - u|_{L^p(0, T-h; E)} \rightarrow 0$ as $h \rightarrow 0$
(ii) $M(t)$ is relatively compact in E for a.e. $t \in [0, T]$.

Theorem 1.5. *Let $p \in [1, \infty]$. Let $M \subset L^p(0, T; E)$ be countable and suppose there exists $\nu \in L^p(0, T)$ with $|u(t)| \leq \nu(t)$ a.e. on $[0, T]$ for all $u \in M$. If $M(t)$ is relatively compact in E for a.e. $t \in [0, T]$, then M is weakly relatively compact in $L^p(0, T; E)$.*

Now, we recall the following definition: A map $\psi : [a, b] \times D \rightarrow 2^Y \setminus \{\emptyset\}$, where $D \subset X$ and $(X, |\cdot|_X)$, $(Y, |\cdot|_Y)$ are two Banach spaces, is said to be (q, p) -Carathéodory ($1 \leq q \leq \infty$, $1 \leq p \leq \infty$) if

- (C1) $\psi(\cdot, x)$ is strongly measurable for each $x \in D$
(C2) $\psi(t, \cdot)$ is upper semicontinuous for a.e. $t \in [a, b]$
(C3) (a) if $1 \leq p < \infty$, there exists $\nu \in L^q(a, b; \mathbb{R}_+)$ and $d \in \mathbb{R}_+$ such that $|\psi(t, x)|_Y \leq \nu(t) + d|x|_X^p$ a.e. on $[a, b]$, for all $x \in D$
(b) if $p = \infty$, for each $\rho > 0$ there exists $\nu_\rho \in L^q(a, b; \mathbb{R}_+)$ such that $|\psi(t, x)|_Y \leq \nu_\rho(t)$ a.e. on $[a, b]$, for all $x \in D$ with $|x|_X \leq \rho$.

2. A GENERAL EXISTENCE PRINCIPLE

The aim of this section is to extend the general existence principles given in [10] for inclusions in $L^p(0, T; E)$, to inclusions in $W^{1,p}(0, T; E)$. Here again E a Banach space with norm $|\cdot|$. This extension allows us to consider boundary-value problems for second order differential inclusions with u' dependence perturbations and, by this, it complements the theory from [8], [9] and [10].

Let $p \in [1, \infty]$ and $q \in [1, \infty[$. Let $r \in [1, \infty]$ be the conjugate exponent of q , that is $1/q + 1/r = 1$. Let $g : [0, T] \times E^2 \rightarrow 2^E$ and let $G : W^{1,p}(0, T; E) \rightarrow 2^{L^q(0, T; E)}$ be the Nemytskii set-valued operator associated to g , p and q , given by

$$G(u) = \{w \in L^q(0, T; E) : w(s) \in g(s, u(s), u'(s)) \text{ a.e. on } [0, T]\}. \quad (2.1)$$

Also consider a single-valued nonlinear operator

$$S : L^q(0, T; E) \rightarrow W^{1,p}(0, T; E).$$

We have the following existence principle for the operator inclusion

$$u \in SG(u), \quad u \in W^{1,p}(0, T; E). \quad (2.2)$$

Theorem 2.1. *Let K be a closed convex subset of $W^{1,p}(0, T; E)$, U a convex relatively open subset of K and $u_0 \in U$. Assume*

- (H1) $SG : \bar{U} \rightarrow P_a(K)$ has closed graph and maps compact sets into relatively compact sets
(H2) $M \subset \bar{U}$, M closed, $M \subset \overline{\text{conv}}(\{u_0\} \cup SG(M))$ implies that M is compact
(H3) $u \notin (1 - \lambda)u_0 + \lambda SG(u)$ for all $\lambda \in]0, 1[$ and $u \in \bar{U} \setminus U$.

Then (2.2) has a solution in \bar{U} .

Proof. Let $D = \overline{\text{conv}}(\{u_0\} \cup SG(\bar{U}))$. Clearly $u_0 \in D \subset K$. Let $P : K \rightarrow \bar{U}$ be given by $P(u) = u$ if $u \in \bar{U}$ and $P(u) = \bar{u}$ if $u \in K \setminus \bar{U}$, where $\bar{u} = (1 - \lambda)u_0 + \lambda u \in \bar{U} \setminus U$, $\lambda \in]0, 1[$. Note P is single-valued, continuous and maps closed sets into closed sets. Let $\tilde{N} : D \rightarrow P_a(K)$, $\tilde{N}(u) = SGP(u)$. It is easy to see that $\tilde{N}(D) \subset D$, the graph of \tilde{N} is closed and \tilde{N} maps compact sets into relatively compact sets. Let D_0 be a closed convex set with $D_0 = \overline{\text{conv}}(\{u_0\} \cup \tilde{N}(D_0 \cap D))$ whose existence is guaranteed

by Lemma 1.3. Since $\tilde{N}(D) \subset D$ we have $D_0 \subset D$ and so $D_0 = \overline{\text{conv}}(\{u_0\} \cup \tilde{N}(D_0))$. Using the definition of P , we obtain

$$P(D_0) \subset \text{conv}(\{u_0\} \cup D_0) = \overline{\text{conv}}(\{u_0\} \cup \tilde{N}(D_0)) = \overline{\text{conv}}(\{u_0\} \cup SG(P(D_0))).$$

In addition, since D_0 is closed, $P(D_0)$ is also closed. Now (H2) guarantees that $P(D_0)$ is compact. Since SG maps compact sets into relatively compact sets, we have that $\tilde{N}(D_0)$ is relatively compact. Then Mazur's Lemma guarantees that D_0 is compact. Now apply the Eilenberg-Montgomery Theorem with $\Xi = \Theta = D_0$, $\Phi = \tilde{N}$ and $\Gamma = \text{identity of } D_0$, to deduce the existence of a fixed point $u \in D_0$ of \tilde{N} . If $u \notin \bar{U}$, then $P(u) = (1 - \lambda)u_0 + \lambda u = (1 - \lambda)u_0 + \lambda SG(P(u))$ for some $\lambda \in]0, 1[$. Since $P(u) \in \bar{U} \setminus U$, this contradicts (H3). Thus $u \in \bar{U}$, so $u = SG(u)$ and the proof is complete. \square

Remark 2.2. Additional regularity for the solutions of (2.2) depends on the values of S . In particular if the values of S are in C_a^1 then so are all solutions of (2.2).

In what follows K will be a closed linear subspace of $W^{1,p}(0, T; E)$, $u_0 = 0$ and U will be the open ball of K ,

$$U = \{u \in K : \|u\| < R\}$$

with respect to an equivalent norm $\|\cdot\|$ on K . For $p \in [1, \infty]$ denote

$$\mu_p := \sup\left\{\frac{|u|_{1,p}}{\|u\|} : u \in K, u \neq 0\right\}, \quad \mu_\infty := \sup\left\{\frac{|u|_\infty}{\|u\|} : u \in K, u \neq 0\right\}.$$

Note that μ_p and μ_∞ are finite because of the equivalence of norms $\|\cdot\|$ and $|\cdot|_{1,p}$ on K and the continuous embedding of $W^{1,p}(0, T; E)$ into $C([0, T]; E)$.

Now we give sufficient conditions on S and g in order that the assumptions (H1)-(H2) be satisfied.

- (S1) There exists a function $k : [0, T]^2 \rightarrow \mathbb{R}_+$ with $k(t, \cdot) \in L^r(0, T)$ and a constant $L > 0$ such that

$$|S(w_1)(t) - S(w_2)(t)| \leq \int_0^T k(t, s) |w_1(s) - w_2(s)| ds$$

for a.e. $t \in [0, T]$, and $|S(w_1)' - S(w_2)'|_p \leq L|w_1 - w_2|_q$ for all $w_1, w_2 \in L^q(0, T; E)$

- (S2) $S : L^q(0, T; E) \rightarrow K$ and for every compact convex subset C of E , S is sequentially continuous from $L_w^1(0, T; C)$ to $W^{1,p}(0, T; E)$. (Here $L_w^1(0, T; C)$ stands for $L^1(0, T; C)$ endowed with the weak topology of $L^1(0, T; E)$)
- (G1) $g : [0, T] \times E^2 \rightarrow P_{kc}(E)$
- (G2) $g(\cdot, z)$ has a strongly measurable selection on $[0, T]$, for every $z \in E^2$
- (G3) $g(t, \cdot)$ is upper semicontinuous for a.e. $t \in [0, T]$
- (G4) If $1 \leq p < \infty$, then $|g(t, z_1, z_2)| \leq \nu(t)$ for a.e. $t \in [0, T]$ and all $z_1, z_2 \in E$ with $|z_1| \leq \mu_0 R$; if $p = \infty$, then $|g(t, z_1, z_2)| \leq \nu(t)$ for a.e. $t \in [0, T]$ and all $z_1, z_2 \in E$ with $|z_1| \leq \mu_\infty R$ and $|z_2| \leq \mu_\infty R$. Here $\nu \in L^q(0, T; \mathbb{R}_+)$.
- (G5) For every separable closed subspace E_0 of the space E , there exists a (q, ∞) -Carathéodory function $\omega : [0, T] \times [0, \mu_0 R] \rightarrow \mathbb{R}_+$, $\omega(t, 0) = 0$, such that for almost every $t \in [0, T]$,

$$\beta_{E_0}(g(t, M, E_0) \cap E_0) \leq \omega(t, \beta_{E_0}(M))$$

for every set $M \subset E_0$ satisfying $|M| \leq \mu_0 R$, and $\varphi = 0$ is the unique solution in $L^\infty(0, T; [0, \mu_0 R])$ to the inequality

$$\varphi(t) \leq \int_0^T k(t, s)\omega(s, \varphi(s))ds \quad \text{a.e. on } [0, T]. \quad (2.3)$$

Here β_{E_0} is the ball measure of non-compactness on E_0 . (Recall that for a bounded set $A \subset E_0$, $\beta_{E_0}(A)$ is the infimum of $\varepsilon > 0$ for which A can be covered by finitely many balls of E_0 with radius not greater than ε)

(SG) For every $u \in \overline{U}$ the set $SG(u)$ is acyclic in K .

Remark 2.3. If S has values in C_a^1 then a sufficient condition for (S1) is to exist a function $\theta \in L^r(0, T; \mathbb{R}_+)$ such that

$$|S(w_1)' - S(w_2)'|_p \leq \int_0^T \theta(s)|w_1(s) - w_2(s)|ds$$

for all $w_1, w_2 \in L^q(0, T; E)$.

Indeed, using Proposition 1.1 and Hölder's inequality, we immediately see that (S1) is satisfied with $k(t, s) = \frac{1}{2}T^{\frac{r-1}{p}}\theta(s)$ and $L = |\theta|_r$.

Remark 2.4. In case that $k(t, \cdot) \in L^\infty(0, T)$ for a.e. $t \in [0, T]$, we may assume that ω in (G5) is a $(1, \infty)$ -Carathéodory function (in order that the integral in (2.3) be defined).

As in [10] we can prove the following existence result.

Theorem 2.5. *Assume (S1)-(S2), (G1)-(G5) and (SG) hold. In addition assume (H3). Then (2.2) has at least one solution u in $K \subset W^{1,p}(0, T; E)$ with $\|u\| \leq R$.*

The proof is based on Theorem 2.1 and consists in showing that conditions (H1)-(H2) are satisfied. We shall use the following analog of [10, lemma 4.4].

Lemma 2.6. *Assume (S1), (S2). Let M be a countable subset of $L^q(0, T; E)$ such that $M(t)$ is relatively compact for a.e. $t \in [0, T]$ and there is a function $\nu \in L^q(0, T; \mathbb{R}_+)$ with $|u(t)| \leq \nu(t)$ a.e. on $[0, T]$, for every $u \in M$. Then the set $S(M)$ is relatively compact in $W^{1,p}(0, T; E)$. In addition S is continuous from M equipped with the relative weak topology of $L^q(0, T; E)$ to $W^{1,p}(0, T; E)$ equipped with its strong topology.*

Proof. Let $M = \{u_n : n \geq 1\}$ and let $\varepsilon > 0$ be arbitrary. As in the proof of [10, lemma 4.3], we can find functions $\widehat{u}_{n,k}$ with values in a compact $\overline{B}_k \subset E$ (\overline{B}_k being a closed ball of a k dimensional subspace of E) such that

$$|u_n - \widehat{u}_{n,k}|_q \leq \varepsilon$$

for every $n \geq 1$. Then assumption (S1) implies

$$|S(u_n) - S(\widehat{u}_{n,k})|_p \leq \|k(t, \cdot)\|_r |u_n - \widehat{u}_{n,k}|_q \leq \varepsilon \|k(t, \cdot)\|_r, \quad (2.4)$$

$$|S(u_n)' - S(\widehat{u}_{n,k})'|_p \leq L |u_n - \widehat{u}_{n,k}|_q \leq \varepsilon L. \quad (2.5)$$

On the other hand, according to Theorem 1.5, the set $\{\widehat{u}_{n,k} : n \geq 1\} \subset L^q(0, T; E)$ is weakly relatively compact in $L^q(0, T; E)$. Then assumption (S2) guarantees that $\{S(\widehat{u}_{n,k}) : n \geq 1\}$ is relatively compact in $W^{1,p}(0, T; E)$. Hence from (2.4) and (2.5) we see that $\{S(\widehat{u}_{n,k}) : n \geq 1\}$ is a relatively compact ε -net of $S(M)$ with

respect to the norm $|\cdot|_{1,p}$, where $\varrho = \max\{L, \|k(t, \cdot)\|_r\}_p$. Since ε was arbitrary we conclude that $S(M)$ is relatively compact in $W^{1,p}(0, T; E)$.

Now suppose that the sequence $(w_m)_m$ converges weakly in $L^q(0, T; E)$ to w and $w_m \in M$ for all $m \geq 1$. In view of the relative compactness of $S(M)$, we may assume that $(S(w_m))_m$ converges in K towards some function $v \in K$. We have to prove

$$v = S(w).$$

For an arbitrary number $\varepsilon > 0$, we have already seen that the proof of [10, lemma 4.3] provides a compact set P_ε and a sequence $(w_m^\varepsilon)_m$ of P_ε -valued functions satisfying,

$$|w_m - w_m^\varepsilon|_q \leq \varepsilon \tag{2.6}$$

for every $m \geq 1$. Now the sequence $(w_m^\varepsilon)_m$ being weakly relatively compact in $L^q(0, T, E)$, a suitable subsequence $(w_{m_j}^\varepsilon)_j$ must be weakly convergent in $L^q(0, T, E)$ towards some w^ε . Then Mazur's Lemma and (2.6) provide

$$|w - w^\varepsilon|_q \leq \varepsilon. \tag{2.7}$$

The triangle inequality yields

$$\begin{aligned} |v - S(w)|_p &\leq |v - S(w_{m_j})|_p + |S(w_{m_j}) - S(w_{m_j}^\varepsilon)|_p \\ &\quad + |S(w_{m_j}^\varepsilon) - S(w^\varepsilon)|_p + |S(w^\varepsilon) - S(w)|_p \end{aligned} \tag{2.8}$$

and

$$\begin{aligned} |v' - S(w)'|_p &\leq |v' - S(w_{m_j})'|_p + |S(w_{m_j})' - S(w_{m_j}^\varepsilon)'|_p \\ &\quad + |S(w_{m_j}^\varepsilon)' - S(w^\varepsilon)'|_p + |S(w^\varepsilon)' - S(w)'|_p. \end{aligned} \tag{2.9}$$

Passing to the limit when j goes to infinity in (2.8), (2.9) and using assumption (S2) we obtain

$$|v - S(w)|_p \leq \limsup_j |S(w_{m_j}) - S(w_{m_j}^\varepsilon)|_p + |S(w^\varepsilon) - S(w)|_p, \tag{2.10}$$

$$|v' - S(w)'|_p \leq \limsup_j |S(w_{m_j})' - S(w_{m_j}^\varepsilon)'|_p + |S(w^\varepsilon)' - S(w)'|_p. \tag{2.11}$$

According to (2.6) and (2.7) we deduce from (2.10), (2.11) and assumption (S1) that

$$|v - S(w)|_p \leq 2\varepsilon \|k(t, \cdot)\|_r, \quad |v' - S(w)'|_p \leq 2\varepsilon L.$$

Hence $|v - S(w)|_{1,p} \leq 2\varepsilon \varrho$. Since ε was arbitrary we must have $v = S(w)$ and the proof is complete. \square

Proof of Theorem 2.5. (a) First we show that $G(u) \neq \emptyset$ and so $SG(u) \neq \emptyset$ for every $u \in \bar{U}$. Indeed, since g takes nonempty compact values and satisfies (G2)-(G3), for each strongly measurable function $u : [0, T] \rightarrow E^2$ there exists a strongly measurable selection w of $g(\cdot, u(\cdot))$ (see [11], Proof of Proposition 3.5 (a)). Next, if $u \in L^p(0, T; E^2)$, (G4) guarantees $w \in L^q(0, T; E)$. Hence $w \in G(u)$.

(b) The values of SG are acyclic according to assumption (SG).

(c) The graph of SG is closed. To show this, let $(u_n, v_n) \in \text{graph}(SG)$, $n \geq 1$, with $|u_n - u|_{1,p}, |v_n - v|_{1,p} \rightarrow 0$ as $n \rightarrow \infty$. Let $v_n = S(w_n)$, $w_n \in L^q(0, T; E)$; $w_n \in G(u_n)$. Since $|u_n - u|_{1,p} \rightarrow 0$, we may suppose that for every $t \in [0, T]$, there exists a compact set $C \subset E^2$ with $\{(u_n(t), u'_n(t)); n \geq 1\} \subset C$. Furthermore, since g is upper semicontinuous by (G3) and has compact values, we have that $g(t, C)$ is compact. Consequently, $\{w_n(t) : n \geq 1\}$ is relatively compact in E . If we also take into account (G4) we may apply Theorem 1.5 to conclude that

(at least for a subsequence) (w_n) converges weakly in $L^q(0, T; E)$ to some w . As in [15, p. 57], since g has convex values and satisfies (G3), we can show that $w \in G(u)$. Furthermore, by using Lemma 2.6 and a suitable subsequence we deduce $S(w_n) \rightarrow S(w)$. Thus $v = S(w)$ and so $(u, v) \in \text{graph}(SG)$.

(d) We show that $SG(M)$ is relatively compact for each compact $M \subset \bar{U}$. Let $M \subset \bar{U}$ be a compact set and (v_n) be any sequence of elements of $SG(M)$. We prove that (v_n) has a convergent subsequence. Let $u_n \in M$ and $w_n \in L^q(0, T; E)$ with

$$v_n = S(w_n) \quad \text{and} \quad w_n \in G(u_n).$$

The set M being compact, we may assume that $|u_n - u|_{1,p} \rightarrow 0$ for some $u \in \bar{U}$. As above, there exists a $w \in G(u)$ with $w_n \rightarrow w$ weakly in $L^q(0, T; E)$ (at least for a subsequence) and $S(w_n) \rightarrow S(w)$. Hence $v_n \rightarrow S(w)$ as we wished. Now (c) and (d) guarantee (H1).

(e) Finally, we check (H2). Suppose $M \subset \bar{U}$ is closed and $M \subset \overline{\text{conv}}(\{0\} \cup SG(M))$. To prove that M is compact it suffices that every sequence (u_n^0) of M has a convergent subsequence. Let $M_0 = \{u_n^0 : n \geq 1\}$. Clearly, there exists a countable subset $M_1 = \{u_n^1 : n \geq 1\}$ of M , $w_n^1 \in G(u_n^1)$ and $v_n^1 = S(w_n^1)$ with $M_0 \subset \overline{\text{conv}}(\{0\} \cup V^1)$, where $V^1 = \{v_n^1 : n \geq 1\}$. Furthermore, there exists a countable subset $M_2 = \{u_n^2 : n \geq 1\}$ of M , $w_n^2 \in G(u_n^2)$ and $v_n^2 = S(w_n^2)$ with $M_1 \subset \overline{\text{conv}}(\{0\} \cup V^2)$, where $V^2 = \{v_n^2 : n \geq 1\}$, and so on. Hence for every $k \geq 1$ we find a countable subset $M_k = \{u_n^k : n \geq 1\}$ of M and correspondingly $w_n^k \in G(u_n^k)$ and $v_n^k = S(w_n^k)$ such that $M_{k-1} \subset \overline{\text{conv}}(\{0\} \cup V^k)$, with $V^k = \{v_n^k : n \geq 1\}$. Let $M^* = \bigcup_{k \geq 0} M_k$. It is clear that M^* is countable, $M_0 \subset M^* \subset M$ and $M^* \subset \overline{\text{conv}}(\{0\} \cup V^*)$, where $V^* = \bigcup_{k \geq 1} V^k$. Since M^* , V^* and $W^* := \{w_n^k : n \geq 1, k \geq 1\}$ are countable sets of strongly measurable functions, we may suppose that their values belong to a separable closed subspace E_0 of E . Since $|w_n^k(t)| \leq \nu(t)$ where $\nu \in L^q(0, T)$, then [10, Lemma 4.3] guarantees

$$\beta_{E_0}(M^*(t)) \leq \beta_{E_0}(V^*(t)) = \beta_{E_0}(S(W^*)(t)) \leq \int_0^T k(t, s) \beta_{E_0}(W^*(s)) ds,$$

while (G5) gives

$$\beta_{E_0}(W^*(s)) \leq \beta_{E_0}(g(s, M^*(s), E_0) \cap E_0) \leq \omega(s, \beta_{E_0}(M^*(s))). \quad (2.12)$$

It follows that

$$\beta_{E_0}(M^*(t)) \leq \int_0^T k(t, s) \omega(s, \beta_{E_0}(M^*(s))) ds.$$

Moreover the function $\varphi(t) = \beta_{E_0}(M^*(t))$ belongs to $L^\infty(0, T; [0, \mu_0 R])$. Consequently, $\varphi \equiv 0$, and so

$$\varphi(t) = \beta_{E_0}(M^*(t)) = 0$$

a.e. on $[0, T]$. Let (v_i^*) be any sequence of V^* and let (w_i^*) be the corresponding sequence of W^* , with $v_i^* = S(w_i^*)$ for all $i \geq 1$. Then, as at step (c), (w_i^*) has a weakly convergent subsequence in $L^q(0, T; E)$, say to w . Also (2.12) together with $\omega(t, 0) = 0$ implies that the set $\{w_i^*(t) : i \geq 1\}$ is relatively compact for a.e. $t \in [0, T]$. From Lemma 2.6 we then have that the corresponding subsequence of $(S(w_i^*)) = (v_i^*)$ converges to $S(w)$ in $W^{1,p}(0, T; E)$. Hence V^* is relatively compact. Now Mazur's Lemma guarantees that the set $\overline{\text{conv}}(\{0\} \cup V^*)$ is compact and so its subset M^* is relatively compact too. Thus M_0 possesses a convergent subsequence as we wished. Now the result follows from Theorem 2.1. \square

3. THE ANTI-PERIODIC SOLUTION OPERATOR

For the rest of this paper E will be a real Hilbert space of inner product (\cdot, \cdot) and norm $|\cdot|$. Consider the anti-periodic boundary value problem

$$\begin{aligned} -u'' - \varepsilon u' &\in Au + g(t, u, u') \quad \text{a.e. on } [0, T] \\ u(0) &= -u(T), \quad u'(0) = -u'(T), \end{aligned} \quad (3.1)$$

in E , where $\varepsilon \in \mathbb{R}$ and $A : D(A) \subset E \rightarrow 2^E \setminus \{\emptyset\}$ is an odd m -dissipative nonlinear operator.

Let us consider the *anti-periodic solution operator* associated to A and ε ,

$$S : L^2(0, T; E) \rightarrow H^2(0, T; E) \cap C_a^1$$

defined by $S(w) := u$, where u is the unique solution of

$$\begin{aligned} -u'' - \varepsilon u' &\in Au + w \quad \text{a.e. on } [0, T] \\ u(0) &= -u(T), \quad u'(0) = -u'(T). \end{aligned} \quad (3.2)$$

The operator S is well defined as it follows from Theorem 3.1 in Aftabizadeh-Aizicovici-Pavel [1]. It is clear that any fixed point u of $N := SG$, where G is the Nemytskii set-valued operator given by (2.1) with $p = q = 2$, is a solution for (3.1).

Theorem 3.1. *The above operator S satisfies (S1) and (S2) for $p = q = 2$ and $K = \overline{C_a^1}$ in $H^1(0, T; E)$ with norm $\|u\| = |u'|_2$.*

Proof. (I) We first show that S satisfies (S1). Let $w_1, w_2 \in L^2(0, T; E)$ and denote $u_i = S(w_i)$, $i = 1, 2$. Then $-u_i'' - \varepsilon u_i' = v_i + w_i$, where $v_i(t) \in Au_i(t)$ a.e. on $[0, T]$. One has

$$-(u_1 - u_2)''(t) - \varepsilon(u_1 - u_2)'(t) = (v_1 - v_2)(t) + (w_1 - w_2)(t).$$

Multiplying by $(u_1 - u_2)(t)$ and using that A dissipative, we obtain

$$\begin{aligned} -(|u_1(t) - u_2(t)|^2)'' + 2|u_1'(t) - u_2'(t)|^2 - \varepsilon(|u_1(t) - u_2(t)|^2)' \\ \leq 2(w_1(t) - w_2(t), u_1(t) - u_2(t)). \end{aligned} \quad (3.3)$$

Consequently,

$$|u_1(t) - u_2(t)|^2 \leq 2 \int_0^T G(t, s)(w_1(s) - w_2(s), u_1(s) - u_2(s)) ds. \quad (3.4)$$

Here G is the Green function of the differential operator $-u'' - \varepsilon u'$ corresponding to the anti-periodic boundary conditions. This yields

$$|S(w_1)(t) - S(w_2)(t)| \leq m \int_0^T |w_1(s) - w_2(s)| ds \quad (3.5)$$

where $m = 2 \max_{(t,s) \in [0,T]^2} G(t, s)$. From (3.3) by integration we obtain

$$\int_0^T |u_1' - u_2'|^2 ds \leq \int_0^T (w_1 - w_2, u_1 - u_2) ds.$$

This together with (3.5) yields

$$|S(w_1)' - S(w_2)'|_2 \leq \sqrt{mT} |w_1 - w_2|_2.$$

(II) The fact that S satisfies (S2) is achieved in several steps: (1) We first show that the graph of S is sequentially closed in $L_w^2(0, T; E) \times H^1(0, T; E)$. In this order,

let $w_j \rightarrow w$ weakly in $L^2(0, T; E)$ and $S(w_j) \rightarrow u$ strongly in $H^1(0, T; E)$. Then $(w_j - w, S(w_j) - S(w)) \rightarrow 0$ strongly in $L^1(0, T; \mathbb{R})$. Now (3.4) implies

$$|S(w_j)(t) - S(w)(t)| \rightarrow 0 \quad \text{as } j \rightarrow \infty.$$

Hence $S(w) = u$.

(2) For each positive integer n we let

$$J_n = \left(J - \frac{1}{n}A\right)^{-1}, \quad A_n = n(J_n - J),$$

where J is the identity map of E . We also consider the operator $S_n : L^2(0, T; E) \rightarrow H^2(0, T; E) \cap C_a^1$, given by $S_n(w) = u_n$, where u_n is the unique solution of

$$\begin{aligned} -u_n'' - \varepsilon u_n' &= A_n u_n + w \quad \text{a.e. on } [0, T] \\ u_n(0) &= -u_n(T), \quad u_n'(0) = -u_n'(T). \end{aligned} \tag{3.6}$$

Then

$$-|u_k''|^2 - \varepsilon(u_k', u_k'') = (A_k u_k, u_k')' - ((A_k u_k)', u_k') + (w, u_k'').$$

Since A_k is dissipative, we have

$$((A_k u_k)', u_k') = \lim_{h \rightarrow 0} \frac{1}{h^2} (A_k u_k(t+h) - A_k u_k(t), u_k(t+h) - u_k(t)) \leq 0.$$

Hence

$$|u_k''|^2 \leq -(A_k u_k, u_k')' - (w, u_k'') - \frac{\varepsilon}{2}(|u_k'|^2)'$$

By integration, since A_k is odd and u_k is anti-periodic, it follows

$$|u_k''|_2^2 = \int_0^T |u_k''|^2 dt \leq - \int_0^T (w, u_k'') dt \leq \frac{1}{2}(|w|_2^2 + |u_k''|_2^2).$$

Consequently,

$$|u_k''|_2 \leq |w|_2. \tag{3.7}$$

Using $2|u'|^2 = (|u|^2)'' - 2(u'', u)$ and $(|u|^2)' = 2(u', u)$ we obtain

$$\begin{aligned} &2 \int_0^T |u_k' - u_m'|^2 dt \\ &= (|u_k - u_m|^2)'(T) - (|u_k - u_m|^2)'(0) - 2 \int_0^T (u_k'' - u_m'', u_k - u_m) dt \\ &= -2 \int_0^T (u_k'' - u_m'', u_k - u_m) dt. \end{aligned} \tag{3.8}$$

On the other hand

$$\begin{aligned} &(u_k'' - u_m'', u_k - u_m) \\ &= -(A_k u_k - A_m u_m, u_k - u_m) - \varepsilon(u_k' - u_m', u_k - u_m) \\ &= -(A_k u_k - A_m u_m, J_k u_k - J_m u_m + \frac{1}{k} A_k u_k - \frac{1}{m} A_m u_m) - \varepsilon(u_k' - u_m', u_k - u_m) \end{aligned}$$

and since $A_k u_k \in A J_k u_k$, $A_m u_m \in A J_m u_m$ and A is dissipative, we obtain

$$-(u_k'' - u_m'', u_k - u_m) \leq (A_k u_k - A_m u_m, \frac{1}{k} A_k u_k - \frac{1}{m} A_m u_m) + \frac{\varepsilon}{2}(|u_k - u_m|^2)'$$

From (3.6) and (3.7), also applying Proposition 1.1 to u_k' , we see that

$$|A_k u_k|_2 \leq |u_k''|_2 + |w|_2 + |\varepsilon| |u_k'|_2 \leq |u_k''|_2 + |w|_2 + |\varepsilon| \frac{T}{2} |u_k''|_2 \leq (2 + |\varepsilon| \frac{T}{2}) |w|_2.$$

Then

$$-\int_0^T (u_k'' - u_m'', u_k - u_m) dt \leq 2(2 + |\varepsilon| \frac{T}{2})^2 |w|_2^2 (\frac{1}{k} + \frac{1}{m}).$$

This together with (3.8) shows that

$$\int_0^T |u_k' - u_m'|^2 dt \leq 2(2 + |\varepsilon| \frac{T}{2})^2 |w|_2^2 (\frac{1}{k} + \frac{1}{m}). \quad (3.9)$$

Thus there exists $u \in K$ with $u_k \rightarrow u$ in K . From (3.9), letting $m \rightarrow \infty$ we have

$$|u_k' - u'|_2^2 \leq \frac{2}{k} (2 + |\varepsilon| \frac{T}{2})^2 |w|_2^2. \quad (3.10)$$

Now we show that u is the solution of (3.2). Since (u_k'') is bounded in $L^2(0, T; E)$ and (u_k'') converges to $w' = u''$ in $\mathcal{D}'(0, T; E)$, we may conclude that

$$u_k'' \rightarrow u'' \quad \text{weakly in } L^2(0, T; E). \quad (3.11)$$

Let \mathcal{A} be the realization of A in $L^2(0, T; E)$, i.e., $\mathcal{A} : L^2(0, T; E) \rightarrow 2L^2(0, T; E)$,

$$\mathcal{A}u = \{v \in L^2(0, T; E) : v(t) \in Au(t) \text{ a.e. on } [0, T]\}.$$

Then $(\mathcal{A}_k u)(t) = A_k u(t)$ a.e. on $[0, T]$, so that (3.11) implies that

$$\mathcal{A}_k u_k \rightarrow -u'' - \varepsilon u' - w \quad \text{weakly in } L^2(0, T; E).$$

Since $u_k \rightarrow u$ strongly in $L^2(0, T; E)$ and \mathcal{A} is m -dissipative in $L^2(0, T; E)$, this implies (see Barbu [5], Proposition II. 3.5) $u \in D(\mathcal{A})$ and $[u, -u'' - \varepsilon u' - w] \in \mathcal{A}$. Thus, u is the solution of (3.2), i.e., $u = S(w)$. Now from (3.10) we see that for each bounded set $M \subset L^2(0, T; E)$ and every $\varepsilon > 0$, there exists a k_0 such that

$$\|S_k(w) - S(w)\| \leq \varepsilon \quad \text{for all } k \geq k_0 \text{ and } w \in M. \quad (3.12)$$

Hence $S_{k_0}(M)$ is an ε -net for $S(M)$.

(3) Now we consider a compact convex subset C of E and a countable set $M \subset L^2(0, T; C)$. We shall prove that for each n , the set $S_n(M)$ is relatively compact in K , equivalently, the set $S_n(M)'$ is relatively compact in $L^2(0, T; E)$. Then, also taking into account (3.12), by Hausdorff's Theorem we shall deduce that $S(M)$ is relatively compact in K as desired. We shall apply Theorem 1.4 to $S_n(M)'$. From (3.12) and assumption (S1) we see that for each n and any bounded $M \subset L^2(0, T; E)$, the set $S_n(M)$ is bounded in K . In addition, using

$$u_n(t) = \int_0^T G(t, s)[A_n u_n(s) + w(s)] ds$$

and the Lipschitz property of A_n , we obtain

$$\begin{aligned} |\tau_h u_n' - u_n'|_2^2 &\leq \int_0^T \left(\int_0^T |G_t(t+h, s) - G_t(t, s)| [2n|u_n(s)| + |w(s)|] ds \right)^2 dt \\ &\leq (2n|u_n|_2 + |w|_2)^2 \int_0^T \int_0^T |G_t(t+h, s) - G_t(t, s)|^2 ds dt. \end{aligned}$$

This implies

$$\sup_{w \in M} |\tau_h S_n(w)' - S_n(w)'|_{L^2(0, T-h; E)} \rightarrow 0 \quad \text{as } h \rightarrow 0. \quad (3.13)$$

We claim that $S_n(M)'(t)$ is relatively compact in E for every $t \in [0, T]$. Indeed, for any $w \in M$, the unique solution $u_n = S_n(w)$ of (3.6) satisfies

$$-u_n'' - \varepsilon u_n' + n u_n = n J_n u_n + w \quad \text{a.e. on } [0, T].$$

If we denote by \tilde{G} the Green function of the operator $-u'' - \varepsilon u' + nu$ corresponding to the boundary conditions $u(0) = -u(T)$, $u'(0) = -u'(T)$, then

$$u_n(t) = \int_0^T \tilde{G}(t, s)[nJ_n u_n(s) + w(s)]ds. \quad (3.14)$$

Using a result by Heinz, the nonexpansivity of J_n and the inclusion $M(s) \subset C$ a.e. on $[0, T]$, from (3.14), we obtain

$$\beta_0(S_n(M)(t)) \leq n \int_0^T \tilde{G}(t, s)\beta_0(S_n(M)(s))ds. \quad (3.15)$$

Here β_0 is the ball measure of non-compactness corresponding to a suitable separable closed subspace of E . Let

$$\varphi(t) = \beta_0(S_n(M)(t)), \quad v(t) = \int_0^T \tilde{G}(t, s)\varphi(s)ds.$$

We have

$$-v'' - \varepsilon v' + nv = \varphi, \quad v(0) = -v(T), \quad v'(0) = -v'(T).$$

According to (3.15), $\varphi \leq nv$. Hence $-v'' - \varepsilon v' \leq 0$. Also since $v \geq 0$ we have $v(0) = v(T) = 0$. The maximum principle for the operator $-u'' - \varepsilon u'$ implies $v \leq 0$ on $[0, T]$. Hence $v \equiv 0$. Thus $\beta_0(S_n(M)(t)) = 0$ for all $t \in [0, T]$, that is $S_n(M)(t)$ is relatively compact in E . As a result, $S_n(M)$ is relatively compact in $C([0, T]; E)$. Next from (3.14) we have

$$u'_n(t) = \int_0^T \tilde{G}_t(t, s)[nJ_n u_n(s) + w(s)]ds,$$

whence $S_n(M)'(t)$ is relatively compact in E . This together with (3.13) via Theorem 1.4 implies that $S_n(M)'$ is relatively compact in $L^2(0, T; E)$. \square

4. SUPERLINEAR INCLUSIONS

In this section we establish an existence result for the anti-periodic problem

$$\begin{aligned} -u'' - \varepsilon u' - s(u) &\in Au + h(t, u, u') \quad \text{a.e. on } [0, T] \\ u(0) &= -u(T), \quad u'(0) = -u'(T) \end{aligned} \quad (4.1)$$

in the Hilbert space E , where $\varepsilon > 0$, $A : D(A) \subset E \rightarrow 2^E \setminus \{\emptyset\}$ is odd m -dissipative, $s : E \rightarrow E$ is continuous with a possible superlinear growth, and $h : [0, T] \times E^2 \rightarrow 2^E$. Let $G : H^1(0, T; E) \rightarrow 2^{L^2(0, T; E)}$ be the Nemytskii set-valued operator associated with $g(t, x, y) = s(x) + h(t, x, y)$, that is

$$G(u) = \{v \in L^2(0, T; E) : v = s(u) + w, \quad w \in \text{sel}_{L^2} h(\cdot, u, u')\},$$

and let S be the anti-periodic solution operator associated to A and ε , already defined in Section 3.

The next result concerns condition (H3) and gives sufficient conditions to obtain a priori bounds of solutions.

Theorem 4.1. *Assume that the following conditions hold:*

- (i) *There exist two even real functions ϕ, ψ such that $\psi \in C^1(E; \mathbb{R})$ and $A = -\partial\phi$ and $s = \psi'$, where $\partial\phi$ stands for the subdifferential of ϕ*

(ii) There are $a, b \in \mathbb{R}_+$ and $\alpha, \gamma \in [1, 2[$, $\beta \in [0, 2[$ with $\beta + \gamma < 2$ such that

$$-(z, y) \leq a|y|^\alpha + b|x|^\beta|y|^\gamma \quad (4.2)$$

for all $x, y \in E$, $z \in h(t, x, y)$, and for a.e. $t \in [0, T]$.

Then there exists a constant $R > 0$ such that $\|u\| = |u'|_2 < R$ for any solution u of

$$u \in \lambda SG(u) \quad (4.3)$$

and every $\lambda \in]0, 1[$.

Proof. Let u be any non-zero solution of (4.3) for some $\lambda \in]0, 1[$. Let $u_\lambda := \frac{1}{\lambda}u$. Then $u = \lambda u_\lambda$ and

$$u_\lambda = S(w), \quad w \in G(u)$$

that is

$$\begin{aligned} -u_\lambda'' - \varepsilon u_\lambda' &\in Au_\lambda + w, \\ w &= s(u) + v, \\ v &\in \text{sel}_{L^2} h(\cdot, u, u'). \end{aligned}$$

Hence

$$-u_\lambda'' - s(u) - \varepsilon u_\lambda' - v \in Au_\lambda.$$

Multiplying by $u' = \lambda u'_\lambda$ and using the formula $(Au_\lambda, u'_\lambda) = -(\phi(u_\lambda))'$ (see [5, p. 189]), we obtain

$$\frac{\lambda}{2}(|u'_\lambda|^2)' + (\psi(u))' + \frac{\varepsilon}{\lambda}|u'|^2 + (v, u') = \lambda(\phi(u_\lambda))'.$$

Thus,

$$\left(\frac{\lambda}{2}|u'_\lambda|^2 + \psi(u) - \lambda\phi(u_\lambda)\right)' + \frac{\varepsilon}{\lambda}|u'|^2 = -(v, u').$$

By integration from 0 to T and taking into account the anti-periodic boundary conditions and the fact that ϕ and ψ are even, we deduce

$$\varepsilon|u'|_2^2 < \frac{\varepsilon}{\lambda}|u'|_2^2 = -\int_0^T (v(t), u'(t))dt.$$

Now using (4.2) and (1.1) we obtain

$$\begin{aligned} \varepsilon|u'|_2^2 &< a|u'|_\alpha^\alpha + b \int_0^T |u|^\beta |u'|^\gamma dt \\ &\leq a|u'|_\alpha^\alpha + b\left(\frac{1}{2}|u'|_1\right)^\beta \int_0^T |u'|^\gamma dt \\ &= a|u'|_\alpha^\alpha + b\frac{1}{2^\beta}|u'|_1^\beta |u'|_\gamma^\gamma. \end{aligned}$$

Since $\alpha, \gamma \in [1, 2[$ there are constants c_1, c_2 such that $|u'|_\alpha \leq T^{\frac{2-\alpha}{2\alpha}}|u'|_2$ and $|u'|_\gamma \leq T^{\frac{2-\gamma}{2\gamma}}|u'|_2$. In addition $|u'|_1 \leq T^{\frac{1}{2}}|u'|_2$. Consequently, one has

$$\varepsilon|u'|_2^2 < C_1|u'|_2^\alpha + C_2|u'|_2^{\beta+\gamma},$$

where the constants C_1, C_2 (independent of u and λ) are:

$$C_1 = aT^{\frac{2-\alpha}{2}}, \quad C_2 = b\frac{1}{2^\beta}T^{\frac{2+\beta-\gamma}{2}}.$$

Now the conclusion follows since $\alpha < 2$ and $\beta + \gamma < 2$. \square

Remark 4.2. The above result is also true if $\alpha = 2$ or $\beta + \gamma = 2$ provided that a , respectively b , is sufficiently small.

Now we are ready to state the main result of this section.

Theorem 4.3. *Let E be a Hilbert space, $\varepsilon > 0$, $s : E \rightarrow E$, $A : E \rightarrow 2^E$ and $h : [0, T] \times E^2 \rightarrow 2^E$. Assume:*

- (i) $s = \psi'$ for some even function $\psi \in C^1(E; \mathbb{R})$, and s sends bounded sets into bounded sets
- (ii) A is an m -dissipative mapping with $A = -\partial\phi$ for some even real function ϕ
- (iii) $h : [0, T] \times E^2 \rightarrow P_{kc}(E)$, $h(\cdot, z)$ has a strongly measurable selection on $[0, T]$ for every $z \in E^2$, $h(t, \cdot)$ is upper semicontinuous for a.e. $t \in [0, T]$, and for each $\tau > 0$ there exists $\nu \in L^2(0, T)$ with $|h(t, z)| \leq \nu(t)$ for a.e. $t \in [0, T]$ and all $z = (z_1, z_2) \in E^2$ with $|z_1| \leq \tau$; in addition there are $a, b \in \mathbb{R}_+$ and $\alpha, \gamma \in [1, 2[$ and $\beta \in [0, \infty[$ such that

$$-(z, y) \leq a|y|^\alpha + b|x|^\beta|y|^\gamma$$

for all $x, y \in E$, $z \in h(t, x, y)$, and for a.e. $t \in [0, T]$

- (iv) There exists $R > 0$ with

$$\varepsilon R^2 \geq aT^{\frac{2-\alpha}{2}} R^\alpha + b\frac{1}{2^\beta} T^{\frac{2+\beta-\gamma}{2}} R^{\beta+\gamma} \quad (4.4)$$

such that for every separable closed subspace E_0 of E , there exists a $(1, \infty)$ -Carathéodory function $\omega : [0, T] \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$ such that for almost every $t \in [0, T]$,

$$\beta_{E_0}(g(t, M, E_0) \cap E_0) \leq \omega(t, \beta_{E_0}(M))$$

(where $g(t, x, y) = s(x) + h(t, x, y)$) for every bounded set $M \subset E_0$, and $\varphi = 0$ is the unique solution in $L^\infty(0, T; \mathbb{R}_+)$ to the inequality

$$\varphi(t) \leq m \int_0^T \omega(s, \varphi(s)) ds \quad \text{a.e. on } [0, T] \quad (4.5)$$

- (v) SG has acyclic values.

Then (4.1) has at least one solution $u \in H^2(0, T; E) \cap C_a^1$ with $\|u\| \leq R$.

Remark 4.4. (a) Note that we do not assume $\beta + \gamma < 2$, so the perturbation term $h(t, u, u')$ can have a superlinear growth in u ; inequality (4.4) guarantees that $\|u\| \neq R$ for each solution of (4.3) and $\lambda \in]0, 1[$. This does not exclude the existence of solutions with $\|u\| > R$.

(b) However, according to Theorem 4.1, if $\beta + \gamma < 2$, then there exists a sufficiently large constant $R_0 > 0$ such that (4.4) holds with equality. In this case R_0 is a bound for all solutions to (4.3).

(c) Sufficient conditions for (v) can be found in [10]. For example (v) always holds if A is single-valued.

5. APPLICATIONS

In this section we are concerned with two applications of Theorem 4.3 to partial differential inclusions.

(I) First we look for a function $u = u(t, x) = u(t)(x)$ solving the problem

$$\begin{aligned} -u_{tt} - \varepsilon u_t + \sigma \Delta_x^{-1}(|u|^{p-2}u) + u &\in h(t, u, u_t) \quad \text{a.e. on } [0, T] \\ u(t, \cdot) &\in H_0^1(\Omega) \quad \text{for a.e. } t \in [0, T] \\ u(0, x) = -u(T, x), \quad u_t(0, x) &= -u_t(T, x) \quad \text{a.e. on } \Omega. \end{aligned} \tag{5.1}$$

Here Ω is a bounded domain of \mathbb{R}^n , $n \geq 3$, $2 < p < 2^* = \frac{2n}{n-2}$, $\varepsilon > 0$, $\sigma \in \mathbb{R}$ and $\Delta_x : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$ is the Laplacian. Also by $|\cdot|$ we mean here the absolute value of a real number.

In this setting we let $E = H_0^1(\Omega)$ with the inner product $(u, v)_{H_0^1(\Omega)} = \int_{\Omega} \nabla u \cdot \nabla v dx$ and norm $|u|_{H_0^1(\Omega)} = (\int_{\Omega} |\nabla u|^2 dx)^{\frac{1}{2}}$, $A(u) = -u$ with $D(A) = H_0^1(\Omega)$ and $s(u) = -\sigma \Delta_x^{-1}(|u|^{p-2}u)$. Note that the conditions (i) and (ii) in Theorem 4.3 hold with

$$\phi(u) = \frac{1}{2} \int_{\Omega} |\nabla u|^2 dx \quad \text{and} \quad \psi(u) = \frac{\sigma}{p} \int_{\Omega} |u|^p dx.$$

Also note that for any bounded $M \subset H_0^1(\Omega)$ the set $s(M)$ is relatively compact in $H_0^1(\Omega)$, that is $\beta_{H_0^1(\Omega)}(s(M)) = 0$. Here $\beta_{H_0^1(\Omega)}$ is the ball measure of non-compactness in $H_0^1(\Omega)$. Indeed, since $p < 2^*$ we may choose an $\theta > 0$ with $p \leq 2^* - \frac{\theta}{(2^*)'}$, where $(2^*)' = \frac{2n}{n+2}$. This guarantees that $(2^*)' \leq \frac{2^* - \theta}{p-1}$. Next the embedding of $H_0^1(\Omega)$ into $L^{2^* - \theta}(\Omega)$ being compact, we have that M is relatively compact in $L^{2^* - \theta}(\Omega)$. Then the set $M_p := \{|u|^{p-2}u : u \in M\}$ is relatively compact in $L^{\frac{2^* - \theta}{p-1}}(\Omega)$ and using the continuous embeddings

$$L^{\frac{2^* - \theta}{p-1}}(\Omega) \subset L^{(2^*)'}(\Omega) \subset H^{-1}(\Omega)$$

we find that M_p is relatively compact in $H^{-1}(\Omega)$. Thus, $s(M) = -\sigma \Delta_x^{-1}(M_p)$ is relatively compact in $H_0^1(\Omega)$ as desired.

From Theorem 4.3 one obtains the following result.

Theorem 5.1. *Let $h : [0, T] \times H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow P_{kc}(H_0^1(\Omega))$ be such that $h(\cdot, u, v)$ has a strongly measurable selection on $[0, T]$ for every $u, v \in H_0^1(\Omega)$, $h(t, \cdot)$ is upper semicontinuous for a.e. $t \in [0, T]$, and for each $\tau > 0$ there exists $\nu \in L^2(0, T)$ such that $|h(t, u, v)|_{H_0^1(\Omega)} \leq \nu(t)$ for a.e. $t \in [0, T]$ and all $u, v \in H_0^1(\Omega)$ with $|u|_{H_0^1(\Omega)} \leq \tau$. Assume there are $a, b, a_0 \in \mathbb{R}_+$ and $\alpha, \gamma \in [1, 2[$ and $\beta \in [0, \infty[$ such that*

$$-(w, v)_{H_0^1(\Omega)} \leq a|v|_{H_0^1(\Omega)}^\alpha + b|u|_{H_0^1(\Omega)}^\beta |v|_{H_0^1(\Omega)}^\gamma$$

for all $u, v \in H_0^1(\Omega)$, $w \in h(t, u, v)$ and for a.e. $t \in [0, T]$, and that for each bounded $M \subset H_0^1(\Omega)$,

$$\beta_{H_0^1(\Omega)}(h(t, M, H_0^1(\Omega))) \leq a_0 \beta_{H_0^1(\Omega)}(M).$$

In addition assume that there exists $R > 0$ with

$$\varepsilon R^2 \geq aT^{\frac{2-\alpha}{2}} R^\alpha + b\frac{1}{2^\beta} T^{\frac{2+\beta-\gamma}{2}} R^{\beta+\gamma}.$$

Then for $a_0 < \frac{1}{mT}$, (5.1) has at least one solution $u \in H^2(0, T; H_0^1(\Omega))$ with

$$|u'|_2 = \left(\int_0^T |u'(t)|_{H_0^1(\Omega)}^2 dt \right)^{\frac{1}{2}} \leq R.$$

Proof. For any bounded M , since $\beta_{H_0^1(\Omega)}(s(M)) = 0$, one has

$$\beta_{H_0^1(\Omega)}(g(t, M, H_0^1(\Omega))) \leq a_0 \beta_{H_0^1(\Omega)}(M).$$

Recall that the space $H_0^1(\Omega)$ is separable. It follows that the unique solution $\varphi \in L^\infty(0, T; \mathbb{R}_+)$ of (4.5) with $\omega(t, \tau) = a_0 \tau$ is $\varphi = 0$ provided that $a_0 m T < 1$. Thus Theorem 4.3 applies. \square

Corollary 5.2. *For every $f \in L^\infty(0, T; H_0^1(\Omega))$ the problem*

$$\begin{aligned} -u_{tt} - \varepsilon u_t + \sigma \Delta_x^{-1}(|u|^{p-2}u) + u &= f(t, x) \quad \text{a.e. on } [0, T] \times \Omega \\ u(t, \cdot) &\in H_0^1(\Omega) \quad \text{for a.e. } t \in [0, T] \\ u(0, x) &= -u(T, x), \quad u_t(0, x) = -u_t(T, x) \quad \text{a.e. on } \Omega. \end{aligned}$$

has at least one solution $u \in H^2(0, T; H_0^1(\Omega))$ with

$$\|u'\|_2 \leq \frac{\|f\|_\infty \sqrt{T}}{\varepsilon}.$$

Here $\|f\|_\infty = \text{ess sup}_{t \in [0, T]} \|f(t)\|_{H_0^1(\Omega)}$.

Proof. In this case $h(t, u, v) = f(t) := f(t, \cdot)$. Consequently all the assumptions of Theorem 5.1 are satisfied for $a = 0$, $b = \|f\|_\infty$, $\alpha = 1$, $\beta = 0$, $\gamma = 1$, $a_0 = 0$, $\nu(t) = \|f(t)\|_{H_0^1(\Omega)}$ and $R = \frac{\|f\|_\infty \sqrt{T}}{\varepsilon}$. \square

(II) For the next application we look for a function $u = u(t, x)$ solving the problem

$$\begin{aligned} -u_{tt} - \varepsilon u_t + \sigma |u|_{L^2(\Omega)}^{p-2} u - \Delta_x u &\in h(t, u, u_t) \quad \text{a.e. on } [0, T] \times \Omega \\ u(t, \cdot) &\in H_0^1(\Omega) \quad \text{for a.e. } t \in [0, T] \\ u(0, x) &= -u(T, x), \quad u_t(0, x) = -u_t(T, x) \quad \text{a.e. on } \Omega. \end{aligned} \tag{5.2}$$

Here again Ω is a bounded domain of \mathbb{R}^n , $p > 2$, $\varepsilon > 0$ and $\sigma \in \mathbb{R}$, but we need no upper bound for p . Now we let $E = L^2(\Omega)$, $A = \Delta_x$ be the Laplace operator with $D(A) = H^2(\Omega) \cap H_0^1(\Omega)$ and $s(u) = -\sigma |u|_{L^2(\Omega)}^{p-2} u$. We note that the conditions (i) and (ii) in Theorem 4.3 hold with

$$\phi(u) = \begin{cases} \frac{1}{2} \int_\Omega |\nabla u|^2 dx, & u \in H^1(\Omega) \\ +\infty, & \text{otherwise.} \end{cases}$$

and $\psi(u) = -\frac{\sigma}{p} |u|_{L^2(\Omega)}^p$. From Theorem 4.3 one obtains the following result.

Theorem 5.3. *Let $h : [0, T] \times L^2(\Omega) \times L^2(\Omega) \rightarrow P_{kc}(L^2(\Omega))$ be such that $h(\cdot, u, v)$ has a strongly measurable selection on $[0, T]$ for every $u, v \in L^2(\Omega)$, $h(t, \cdot)$ is upper semicontinuous for a.e. $t \in [0, T]$, and for every $\tau > 0$ there exists $\nu \in L^2(0, T)$ such that $|h(t, u, v)|_{L^2(\Omega)} \leq \nu(t)$ for a.e. $t \in [0, T]$ and all $u, v \in L^2(\Omega)$ with $|u|_{L^2(\Omega)} \leq \tau$. Assume there are $a, b, a_0 \in \mathbb{R}_+$ and $\alpha, \gamma \in [1, 2[$ and $\beta \in [0, \infty[$ such that*

$$-(w, v)_{L^2(\Omega)} \leq a |v|_{L^2(\Omega)}^\alpha + b |u|_{L^2(\Omega)}^\beta |v|_{L^2(\Omega)}^\gamma$$

for all $u, v \in L^2(\Omega)$, $w \in h(t, u, v)$ and for a.e. $t \in [0, T]$, and that for each bounded $M \subset L^2(\Omega)$,

$$\beta_{L^2(\Omega)}(h(t, M, L^2(\Omega))) \leq a_0 \beta_{L^2(\Omega)}(M).$$

In addition assume that there exists $R > 0$ with

$$\varepsilon R^2 \geq a T^{\frac{2-\alpha}{2}} R^\alpha + b \frac{1}{2^\beta} T^{\frac{2+\beta-\gamma}{2}} R^{\beta+\gamma}.$$

Then for sufficiently small $|\sigma|$ and a_0 (5.2) has a solution $u \in H^2(0, T; L^2(\Omega))$ with

$$|u'|_2 = \left(\int_0^T |u'(t)|_{L^2(\Omega)}^2 dt \right)^{1/2} \leq R.$$

Proof. For any $u, v \in L^2(\Omega)$ with $|u|_{L^2(\Omega)}, |v|_{L^2(\Omega)} \leq \eta$, we have

$$\begin{aligned} |s(u) - s(v)|_{L^2(\Omega)} &= |\sigma| \left| |u|_{L^2(\Omega)}^{p-2} u - |v|_{L^2(\Omega)}^{p-2} v \right|_{L^2(\Omega)} \\ &\leq |\sigma| \left(|u|_{L^2(\Omega)}^{p-2} (u - v) + (|u|_{L^2(\Omega)}^{p-2} - |v|_{L^2(\Omega)}^{p-2}) v \right)_{L^2(\Omega)} \\ &\leq |\sigma| (\eta^{p-2} |u - v|_{L^2(\Omega)} + (p-2) \eta^{p-2} |u - v|_{L^2(\Omega)}) \\ &= |\sigma| (p-1) \eta^{p-2} |u - v|_{L^2(\Omega)}. \end{aligned}$$

Hence for any bounded $M \subset L^2(\Omega)$ one has

$$\beta_{L^2(\Omega)}(g(t, M, L^2(\Omega))) \leq [|\sigma|(p-1)|M|^{p-2} + a_0] \beta_{L^2(\Omega)}(M)$$

where, as above, $g(t, u, v) = s(u) + h(t, u, v)$, and $|M| = \sup_{u, v \in M} |u - v|_{L^2(\Omega)}$. It is easily seen that the unique solution $\varphi \in L^\infty(0, T; \mathbb{R}_+)$ of (4.5) with

$$\omega(t, \tau) = [|\sigma|(p-1)\eta^{p-2} + a_0]\tau$$

where $\eta = R \max\{1, \sqrt{T}/2\}$, is $\varphi = 0$ provided that $|\sigma|$ and a_0 are small enough. Thus Theorem 4.3 applies. \square

Corollary 5.4. *For every $f \in L^\infty(0, T; L^2(\Omega))$, if $|\sigma|$ is sufficiently small the problem*

$$\begin{aligned} -u_{tt} - \varepsilon u_t + \sigma |u|_{L^2(\Omega)}^{p-2} u - \Delta_x u &= f(t, x) \quad \text{a.e. on } [0, T] \times \Omega \\ u(t, \cdot) &\in H_0^1(\Omega) \quad \text{for a.e. } t \in [0, T] \\ u(0, x) &= -u(T, x), \quad u_t(0, x) = -u_t(T, x) \quad \text{a.e. on } \Omega. \end{aligned}$$

has at least one solution $u \in H^2(0, T; L^2(\Omega))$ with $|u'|_2 \leq \frac{|f|_\infty \sqrt{T}}{\varepsilon}$. Here $|f|_\infty = \text{ess sup}_{t \in [0, T]} |f(t)|_{L^2(\Omega)}$.

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