

EXISTENCE AND NONEXISTENCE FOR SINGULAR SUBLINEAR PROBLEMS ON EXTERIOR DOMAINS

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ABSTRACT. In this article we study the existence of radial solutions of $\Delta u + K(|x|)f(u) = 0$ on the exterior of the ball of radius $R > 0$ centered at the origin in \mathbb{R}^N with $u = 0$ on ∂B_R , and $\lim_{|x| \rightarrow \infty} u(x) = 0$ where $N > 2$, $f(u) \sim \frac{-1}{|u|^{q-1}u}$ for u near 0 with $0 < q < 1$, and $f(u) \sim |u|^{p-1}u$ for large $|u|$ with $0 < p < 1$. Also, $K(|x|) \sim |x|^{-\alpha}$ with $N + q(N - 2) < \alpha < 2(N - 1)$ for large $|x|$.

1. INTRODUCTION

In this article we study the radial solutions of:

$$\Delta u + K(|x|)f(u) = 0, \quad x \in \mathbb{R}^N \setminus B_R \quad (1.1)$$

$$u = 0 \quad \text{on } \partial(\mathbb{R}^N \setminus B_R) \quad (1.2)$$

$$u \rightarrow 0 \quad \text{as } |x| \rightarrow \infty \quad (1.3)$$

where B_R is the ball of radius $R > 0$ centered at the origin in \mathbb{R}^N , $K(x) > 0$ and $u : \mathbb{R}^N \rightarrow \mathbb{R}$ with $N > 2$. In addition, we suppose $f : \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}$ is locally Lipschitz and

(H1) f is odd, there exists $\beta > 0$ such that $f < 0$ on $(0, \beta)$, $f > 0$ on (β, ∞) .

(H2) $g_1 : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and

$$f(u) = \frac{-1}{|u|^{q-1}u} + g_1(u)$$

where $0 < q < 1$ and $g_1(0) = 0$.

(H3) $g_2 : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and $f(u) = |u|^{p-1}u + g_2(u)$, where $0 < p < 1$ and $\lim_{u \rightarrow +\infty} g_2(u)/|u|^p = 0$.

We let $F(u) = \int_0^u f(s) ds$. Since f is odd it follows that F is even and from (H2) it follows that f is integrable near $u = 0$. Thus F is continuous and $F(0) = 0$. It also follows that F is bounded below by $-F_0$ with $F_0 > 0$ and from (H3) we see there exists γ with $0 < \beta < \gamma$ such that

(H4) $F < 0$ on $(0, \gamma)$, $F > 0$ on (γ, ∞) , and $F > -F_0$ on \mathbb{R} .

(H5) K and K' are continuous on $[R, \infty)$ with $K(r) > 0$, $2(N - 1) + \frac{rK'}{K} > 0$, $N + q(N - 2) < \alpha < 2(N - 1)$ and $\lim_{r \rightarrow \infty} rK'/K = -\alpha$.

(H6) There exists $K_1 > 0$ such that $\lim_{r \rightarrow \infty} r^\alpha K(r) = K_1 > 0$.

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Interest in the topic for this article comes from recent papers [2, 7, 9, 10] about solutions of differential equation problems on exterior domains. In [1] we studied (1.1)–(1.3) with $K(r) \sim r^{-\alpha}$, where f is singular at 0 and grows superlinearly at ∞ , with various values of α . We proved existence of an infinite number of solutions. In this article we consider the case when f is singular at 0 and grows sublinearly at ∞ . In this article we prove the following results.

Theorem 1.1. *Let $N > 2$, $R > 0$, $0 < p, q < 1$, $N + q(N - 2) < \alpha < 2(N - 1)$, and suppose (H1)–(H6) hold. Then given a non-negative integer, n_0 , then there are solutions u_0, u_1, \dots, u_{n_0} of (1.1)–(1.3) where u_k has exactly k zeros on (R, ∞) and $\lim_{r \rightarrow \infty} u_k(r) = 0$ if R is sufficiently small.*

Theorem 1.2. *Let $N > 2$, $R > 0$, $0 < p, q < 1$, $N + q(N - 2) < \alpha < 2(N - 1)$, and suppose (H1)–(H6) hold. Then there are no radial solutions of (1.1)–(1.3) if $R > 0$ is sufficiently large.*

2. PRELIMINARIES

Since we are interested in studying radial solutions of (1.1)–(1.3), we assume that $r = |x| = \sqrt{x_1^2 + x_2^2 + \dots + x_N^2}$, $u(r) = u(|x|)$ where $x \in \mathbb{R}^N$ and u satisfies

$$u''(r) + \frac{N-1}{r}u'(r) + K(r)f(u(r)) = 0 \quad \text{on } (R, \infty), \quad (2.1)$$

$$u(R) = 0, \quad \lim_{r \rightarrow \infty} u(r) = 0. \quad (2.2)$$

To prove existence we make the change of variables

$$u(r) = v(r^{2-N}). \quad (2.3)$$

Then

$$\begin{aligned} u'(r) &= (2-N)r^{1-N}v'(r^{2-N}), \\ u''(r) &= (2-N)(1-N)r^{-N}v'(r^{2-N}) + (2-N)^2r^{2(1-N)}v''(r^{2-N}). \end{aligned}$$

Letting $t = r^{2-N}$ and $r = t^{\frac{1}{2-N}}$ in (2.1)–(2.2) gives

$$v''(t) + h(t)f(v(t)) = 0 \quad \text{for } 0 < t < R^{2-N} \quad (2.4)$$

where from (H1)–(H6),

$$h(t) = \frac{1}{(N-2)^2}t^{\frac{2(N-1)}{2-N}}K(t^{\frac{1}{2-N}}) \sim \frac{t^{-\tilde{\alpha}}}{(N-2)^2} \quad \text{with } \tilde{\alpha} = \frac{2(N-1) - \alpha}{N-2} > 0. \quad (2.5)$$

Note that $2 - \tilde{\alpha} = \frac{\alpha-2}{N-2} > 0$. Also from (H5) and (H6) it follows that there is a constant $h_1 > 0$ with

$$\lim_{t \rightarrow 0^+} t^{\tilde{\alpha}}h(t) = h_1, \quad h'(t) < 0 \text{ on } (0, R^{2-N}], \quad 0 < \tilde{\alpha} + q < 1. \quad (2.6)$$

Then there are $h_0 > 0$ and $h_2 > 0$ such that

$$h_0 \leq t^{\tilde{\alpha}}h(t) \leq h_2 \quad \text{on } (0, R^{2-N}]. \quad (2.7)$$

We now consider (2.4) with

$$v(0) = 0, \quad v'(0) = a \geq 0 \quad (2.8)$$

and we try to find $a \geq 0$ such that $v(R^{2-N}) = 0$. We write v_a to emphasize the dependence of v on a . Let $a \geq 0$. We first show that there is a solution v_a of equation (2.4) on $(0, \epsilon)$ for small ϵ along with (2.8) and v_a, v'_a continuous on $[0, \epsilon)$.

This is a bit lengthy so we postpone this proof to the Appendix. We now assume v_a solves (2.4) on $(0, \epsilon)$ and v_a, v'_a continuous on $[0, \epsilon)$.

Next let $(0, B) \subset (0, R^{2-N})$ be the maximal open interval where the solution of (2.4) exists along with (2.8). We will show $B = R^{2-N}$. First, from the proof in the appendix we have that there exists $\epsilon > 0$ such that $0 < \epsilon \leq B \leq R^{2-N}$.

Now we define the energy of solution (2.4), (2.8) as

$$E_a(t) = \frac{1}{2} \frac{v_a'^2(t)}{h(t)} + F(v_a(t)) \quad \text{for } 0 < t < B. \quad (2.9)$$

Differentiating E_a , using (2.4) and since we know from (2.6) that $h'(t) < 0$, then

$$E_a'(t) = -\frac{v_a'^2(t)h'(t)}{2h^2(t)} \geq 0 \quad \text{on } (0, B). \quad (2.10)$$

Thus E_a is nondecreasing on $(0, B)$. Therefore,

$$0 = \lim_{t \rightarrow 0^+} E_a(t) \leq E_a(t) = \frac{1}{2} \frac{v_a'^2(t)}{h(t)} + F(v_a(t)) \quad (2.11)$$

so it follows that

$$E_a(t) > 0 \quad \text{for } 0 < t < B. \quad (2.12)$$

Next we see that

$$\left(\frac{1}{2} v_a'^2(t) + h(t)F(v_a(t)) \right)' = h'(t)F(v_a(t)). \quad (2.13)$$

Now let us show for fixed $a \geq 0$ that v_a and v'_a are continuous on $[0, R^{2-N}]$.

Lemma 2.1. *Assume (H1)–(H6) hold, $N > 2$, and $a \geq 0$. Suppose v_a solves (2.4). Then $|v_a(t)| \leq C$ and $|v'_a(t)| \leq C$ for some constant C on $[0, R^{2-N}]$ and v_a, v'_a are continuous on $[0, R^{2-N}]$.*

Proof. We first assume that there is a $t_{a,\gamma} \in [0, B)$ such that $v_a(t_{a,\gamma}) = \gamma$ and $0 \leq v_a < \gamma$ on $[0, t_{a,\gamma})$.

We know from (H4) that $F(v_a) \leq 0$ when $t \in [0, t_{a,\gamma}]$ so we have

$$0 < \frac{1}{2} \frac{v_a'^2(t)}{h(t)} + F(v_a(t)) \leq \frac{1}{2} \frac{v_a'^2(t)}{h(t)} \quad \text{on } (0, t_{a,\gamma}).$$

Thus $v'_a > 0$ on $[0, t_{a,\gamma}]$. Also if we multiply (2.4) by v_a^q , use (H2), and integrate by parts on $(0, t)$ this gives

$$v_a^q v'_a - \int_0^t q v_a^{q-1}(s) v_a'^2(s) ds + \int_0^t h(s) v_a^q(s) g_1(v_a(s)) ds = \int_0^t h(s) ds. \quad (2.14)$$

Thus

$$v_a^q v'_a + \int_0^t h(s) v_a^q(s) g_1(v_a(s)) ds \geq \int_0^t h(s) ds. \quad (2.15)$$

Integrating (2.15) again and using (2.7) gives

$$\begin{aligned} \frac{v_a^{q+1}(t)}{q+1} + \int_0^t \int_0^s h(x) v_a^q(x) g_1(v_a(x)) dx ds &= \int_0^t \int_0^s h(x) dx ds \\ &\geq \frac{h_0 t^{2-\tilde{\alpha}}}{(2-\tilde{\alpha})(1-\tilde{\alpha})}. \end{aligned} \quad (2.16)$$

Let L_1 be the Lipschitz constant for g_1 on $[0, \gamma]$ so then $|g_1(v_a)| \leq L_1 v_a$ on $[0, t_{a,\gamma}]$. using this and since $v'_a > 0$ on $[0, t_{a,\gamma}]$ then:

$$\begin{aligned} \int_0^t \int_0^s h(x) v_a^q(x) g_1(v_a(x)) dx ds &\leq L_1 \int_0^t \int_0^s h(x) v_a^{q+1}(x) dx ds \\ &\leq L_1 v_a^{q+1}(t) \int_0^t \int_0^s h(x) dx ds. \end{aligned}$$

using this in (2.16) and using (2.7) again we see that

$$\begin{aligned} \frac{h_0 t^{2-\tilde{\alpha}}}{(2-\tilde{\alpha})(1-\tilde{\alpha})} &\leq v_a^{q+1}(t) \left[\frac{1}{q+1} + \frac{L_1 h_2 t^{2-\tilde{\alpha}}}{(2-\tilde{\alpha})(1-\tilde{\alpha})} \right] \\ &\leq v_a^{q+1}(t) \left[\frac{1}{q+1} + \frac{L_1 h_2 R^{(2-N)(2-\tilde{\alpha})}}{(2-\tilde{\alpha})(1-\tilde{\alpha})} \right]. \end{aligned}$$

Therefore

$$v_a(t) \geq C_1 t^{\frac{2-\tilde{\alpha}}{1+q}} \quad \text{on } [0, t_{a,\gamma}] \quad (2.17)$$

where

$$C_1 = \left[\frac{h_0(q+1)}{(2-\tilde{\alpha})(1-\tilde{\alpha}) + L_1 h_2(q+1) R^{(2-N)(2-\tilde{\alpha})}} \right]^{\frac{1}{q+1}} > 0.$$

Evaluating (2.17) at $t = t_{a,\gamma}$ gives

$$t_{a,\gamma} \leq \left(\frac{\gamma}{C_1} \right)^{\frac{1+q}{2-\tilde{\alpha}}}. \quad (2.18)$$

Then from (2.17) and (2.7) we see that

$$\frac{h(t)}{v_a^q(t)} \leq \frac{h_2}{C_1^q} t^{\frac{-\tilde{\alpha}-2q}{1+q}} \quad \text{on } (0, t_{a,\gamma}].$$

Rewriting (2.4) and substituting gives

$$v_a''(t) = \frac{h(t)}{v_a^q(t)} - h(t)g_1(v_a(t)) \leq \frac{h_2}{C_1^q} t^{\frac{-\tilde{\alpha}-2q}{1+q}} + h_2 L_1 t^{-\tilde{\alpha}} \gamma \quad \text{on } (0, t_{a,\gamma}]. \quad (2.19)$$

Integrating on $(0, t)$ gives

$$v_a'(t) \leq a + C_2 t^{\frac{1-\tilde{\alpha}-q}{1+q}} + C_3 t^{1-\tilde{\alpha}} \quad \text{on } [0, t_{a,\gamma}] \quad (2.20)$$

where $C_2 = \frac{h_2(1+q)}{C_1^q(1-\tilde{\alpha}-q)}$, $C_3 = \frac{h_2 L_1 \gamma}{1-\tilde{\alpha}}$. Integrating (2.20) on $(0, t)$ we have

$$v_a(t) \leq at + C_4 t^{\frac{2-\tilde{\alpha}}{1+q}} + \frac{C_3}{2-\tilde{\alpha}} t^{2-\tilde{\alpha}} \quad \text{on } [0, t_{a,\gamma}] \quad (2.21)$$

where

$$C_4 = \frac{h_2(1+q)^2}{C_1^q(1-\tilde{\alpha}-q)(2-\tilde{\alpha})}.$$

Evaluating (2.21) at $t = t_{a,\gamma}$ and using (2.18) we obtain

$$\gamma \leq t_{a,\gamma} \left(a + C_4 \left(\frac{\gamma}{C_1} \right)^{\frac{1-\tilde{\alpha}-q}{2-\tilde{\alpha}}} + \frac{C_3}{2-\tilde{\alpha}} \left(\frac{\gamma}{C_1} \right)^{\frac{(1-\tilde{\alpha})(1+q)}{2-\tilde{\alpha}}} \right) = t_{a,\gamma} (a + C_5) \quad (2.22)$$

where

$$C_5 = C_4 \left(\frac{\gamma}{C_1} \right)^{\frac{1-\tilde{\alpha}-q}{2-\tilde{\alpha}}} + \frac{C_3}{2-\tilde{\alpha}} \left(\frac{\gamma}{C_1} \right)^{\frac{(1-\tilde{\alpha})(1+q)}{2-\tilde{\alpha}}}.$$

From (2.22) we have

$$\frac{1}{t_{a,\gamma}} \leq \frac{a + C_5}{\gamma}. \tag{2.23}$$

Now from (2.20) and for $t \in [0, t_{a,\gamma}]$ we obtain

$$0 \leq v'_a(t) \leq a + C_2 t_{a,\gamma}^{\frac{1-\tilde{\alpha}-q}{1+q}} + C_3 t_{a,\gamma}^{1-\tilde{\alpha}} \leq a + C_6 \quad \text{on } [0, t_{a,\gamma}] \tag{2.24}$$

where $C_6 = C_2 R^{\frac{(2-N)(1-\tilde{\alpha}-q)}{1+q}} + C_3 R^{(2-N)(1-\tilde{\alpha})}$. Thus $|v'_a|$ is bounded on $[0, t_{a,\gamma}]$ if $t_{a,\gamma} \leq B$.

Now continuing to assume $t_{a,\gamma} \leq B$ we integrate (2.13) on $(t_{a,\gamma}, t)$, using (2.24), $h' < 0$, and $-F_0 \leq F(v_a)$ (by (H4)) then we obtain

$$\begin{aligned} \frac{1}{2} v_a'^2(t) - h(t)F_0 &\leq \frac{1}{2} v_a'^2(t_{a,\gamma}) + h(t)F(v_a) \\ &= \frac{1}{2} v_a'^2(t_{a,\gamma}) + \int_{t_{a,\gamma}}^t h'(s)F(v_a(s)) ds \\ &\leq \frac{1}{2} (a + C_6)^2 - \int_{t_{a,\gamma}}^t h'(s)F_0 ds \\ &= \frac{1}{2} (a + C_6)^2 - h(t)F_0 + h(t_{a,\gamma})F_0. \end{aligned}$$

using (2.23) in the above we have

$$\frac{1}{2} v_a'^2(t) \leq \frac{1}{2} (a + C_6)^2 + h(t_{a,\gamma})F_0 \leq \frac{1}{2} (a + C_6)^2 + h_2 F_0 \left(\frac{a + C_5}{\gamma} \right)^\alpha. \tag{2.25}$$

Thus it follows from (2.25) and standard inequalities that $|v'_a|$ is bounded as

$$|v'_a| \leq a + C_7 \quad \text{on } [0, B] \tag{2.26}$$

for some C_7 that does not depend on a if $0 < t_{a,\gamma} \leq B$. Then

$$|v_a| = \left| \int_0^t v'_a ds \right| \leq (a + C_7)t \leq (a + C_7)B \quad \text{on } [0, B] \tag{2.27}$$

so $|v_a|$ is also bounded on $[0, B]$ if $t_{a,\gamma} \leq B$.

On the other hand if $0 \leq v_a < \gamma$ on $[0, B]$ then a similar argument shows that (2.17) and (2.20) hold on $[0, B]$ and so again we see that $|v_a|, |v'_a|$ are bounded on $[0, B]$.

Thus $\lim_{t \rightarrow B^-} v_a(t) = D \in \mathbb{R}$. Also since $h(t)F(v_a(t))$ and $h'(t)F(v_a(t))$ are continuous on $[\epsilon, B]$ it follows by integrating (2.13) on $[\epsilon, B]$ that $\lim_{t \rightarrow B^-} v'_a(t) = D_1 \in \mathbb{R}$. From (2.12) we know $0 < E_a(t) \leq \frac{1}{2} \frac{D_1^2}{h(B)} + F(D)$ on $[0, B]$ so D and D_1 cannot both be zero. If $B < R^{2-N}$ then the solution v_a can be extended to $[0, B + \epsilon)$ for some $\epsilon > 0$ by using the fact that D, D_1 are not both zero for if $D \neq 0$ then we can just use the standard existence theorem from differential equations and if $D = 0$ then $D_1 \neq 0$ and we can use the contraction mapping principle as we did in the appendix which contradicts the definition of B . Thus we see $B = R^{2-N}$. Also since v_a, v'_a are bounded on $[0, R^{2-N})$ then we see $\lim_{t \rightarrow (R^{2-N})^-} v_a$ exists and $\lim_{t \rightarrow (R^{2-N})^-} v'_a$ exists. Thus v_a, v'_a are continuous on $[0, R^{2-N}]$. This completes the proof. \square

Lemma 2.2. *Let $N > 2$, $a \geq 0$. Assume (H1)–(H6) hold, and suppose $v_a(t)$ solves (2.4), (2.8). Then the solutions $v_a(t)$ continuously depend on the parameter $a \geq 0$ on $[0, R^{2-N}]$.*

Proof. Let $0 \leq a_1 < a_2$. Since v_a, v'_a are continuous on $[0, R^{2-N}]$ it follows from (2.26) and (2.27) that v_a, v'_a are bounded on $[0, R^{2-N}]$. Then notice from (2.26) and (2.27) we have

$$|v'_a(t)| \leq a_2 + C_7 \quad \text{on } [0, R^{2-N}] \quad \forall a \text{ with } 0 \leq a_1 \leq a \leq a_2, \quad (2.28)$$

$$|v_a(t)| \leq (a_2 + C_7)R^{2-N} \quad \text{on } [0, R^{2-N}] \quad \forall a \text{ with } 0 \leq a_1 \leq a \leq a_2. \quad (2.29)$$

Thus we see that $|v'_a|$ and $|v_a|$ are uniformly bounded on $[0, R^{2-N}]$ for all a with $0 \leq a_1 \leq a \leq a_2$.

Next, let $a^* \geq 0$ with $0 \leq a_1 \leq a^* \leq a_2$. We will now show that $v_a \rightarrow v_{a^*}$ uniformly on $[0, R^{2-N}]$ as $a \rightarrow a^*$. We prove this by contradiction so suppose not. Then there exist A_j with $a_1 \leq A_j \leq a_2$ such that $A_j \rightarrow a^*$ as $j \rightarrow \infty$, $t_j \in [0, R^{2-N}]$ and there is an $\epsilon_2 > 0$ such that

$$|v_{A_j}(t_j) - v_{a^*}(t_j)| \geq \epsilon_2 \quad \forall j. \quad (2.30)$$

Since $A_j \rightarrow a^*$ as $j \rightarrow \infty$ and $0 \leq a_1 \leq A_j \leq a_2$, by (2.28), (2.29) we see that v_{A_j} and v'_{A_j} are uniformly bounded on $[0, R^{2-N}]$ and therefore the v_{A_j} are equicontinuous on $[0, R^{2-N}]$. Then by the Arzela-Ascoli theorem there is a subsequence $v_{A_{j_l}}$ of v_{A_j} such that $v_{A_{j_l}} \rightarrow v_{a^*}$ uniformly on $[0, R^{2-N}]$. So as $l \rightarrow \infty$,

$$0 \leftarrow |v_{A_{j_l}}(t_{j_l}) - v_{a^*}(t_{j_l})| \geq \epsilon_2 > 0 \quad \text{which is impossible.}$$

Thus v_a varies continuously with a on $[0, R^{2-N}]$ for all a with $0 \leq a_1 \leq a \leq a_2$. This completes the proof. \square

Lemma 2.3. *Let $v_a(t)$ satisfy (2.4), (2.8) and assume that (H1)–(H6) hold. Then $\lim_{a \rightarrow \infty} \max_{[0, R^{2-N}]} v_a(t) = \infty$. In addition, if $v_a(t)$ has a first local maximum, M_a , with $0 < M_a \leq R^{2-N}$, then $v_a(M_a) \rightarrow \infty$ as $a \rightarrow \infty$. Further, if a is sufficiently large, then v_a is increasing on $[0, R^{2-N}]$ and $v_a(R^{2-N}) \rightarrow \infty$ as $a \rightarrow \infty$.*

Proof. We assume by the way of contradiction that $\max_{[0, R^{2-N}]} v_a(t) \leq C_8$ for some constant $C_8 > 0$ which does not depend on a for a large. Since $f(v_a) = -\frac{1}{|v|^{q-1}v_a} + g_1(v_a)$ and $g_1(v_a)$ is continuous on $[0, C_8]$ then there is a $C_9 > 0$ such that $|g_1(v_a)| \leq C_9$ on $[0, R^{2-N}]$. Now either $v'_a > 0$ or v_a has a local maximum M_a and $v'_a > 0$ on $[0, M_a)$. We show that v_a cannot have a local maximum M_a for large a .

Integrating (2.4) over $(0, t)$ and estimating gives

$$v'_a(t) = a + \int_0^t h(s) \frac{1}{|v|^{q-1}v_a} ds - \int_0^t h(s)g_1(v_a) ds \geq a - C_9 \int_0^t h(s) ds. \quad (2.31)$$

Recalling from (2.6) that $\tilde{\alpha} + q < 1$ and $q > 0$ it follows that $\tilde{\alpha} < 1$. Also from (2.7) we have $-h(t) \geq -h_2 t^{-\tilde{\alpha}}$. Then using this in (2.31) implies

$$v'_a(t) \geq a - \frac{C_9 h_2}{1 - \tilde{\alpha}} t^{1-\tilde{\alpha}}. \quad (2.32)$$

Now if v_a has a local maximum then evaluating (2.32) at M_a gives

$$\frac{C_9 h_2}{1 - \tilde{\alpha}} R^{(2-N)(1-\tilde{\alpha})} \geq \frac{C_9 h_2}{1 - \tilde{\alpha}} M_a^{1-\tilde{\alpha}} \geq a \quad (2.33)$$

but the right-hand side goes to infinity as $a \rightarrow \infty$ while the left-hand side is fixed and thus we obtain a contradiction. Thus we see if $a > 0$ is sufficiently large and v_a is bounded above by a constant that is independent of a then $v'_a > 0$ on $[0, R^{2-N}]$. Next integrating (2.32) on $(0, t)$ we obtain:

$$C_8 \geq v_a(t) \geq at - \frac{C_9 h_2}{(1 - \tilde{\alpha})(2 - \tilde{\alpha})} t^{2 - \tilde{\alpha}}. \quad (2.34)$$

Thus

$$C_8 \geq v_a(R^{2-N}) \geq aR^{2-N} - \frac{C_9 h_2}{(1 - \tilde{\alpha})(2 - \tilde{\alpha})} (R^{2-N})^{2 - \tilde{\alpha}} \quad (2.35)$$

therefore the right-hand side of (2.35) approaches infinity as a approaches infinity, but the left-hand side is bounded by C_8 . so we have a contradiction. Thus $\lim_{a \rightarrow \infty} \max_{[0, R^{2-N}]} v_a(t) = \infty$.

Now we show that if v_a has a first local maximum, M_a , on $[0, R^{2-N}]$, then $\lim_{a \rightarrow \infty} v_a(M_a) = \infty$. For if not we may again appeal to (2.33) as we did earlier to again get a contradiction. Thus the assumption that $v_a(M_a)$ is bounded is false. Therefore if $M_a \in [0, R^{2-N}]$ exists, then

$$\lim_{a \rightarrow \infty} v_a(M_a) = \infty. \quad (2.36)$$

Next we show that $v'_a > 0$ on $[0, R^{2-N}]$ if a is sufficiently large. So suppose not. Then there exists a first local maximum, M_a , of v_a , with $0 < M_a \leq R^{2-N}$. From (2.10)–(2.12) we have $E_a(t) > 0$ and $E'_a(t) \geq 0$. Thus for $0 \leq t \leq M_a$ we have

$$\frac{1}{2} \frac{v_a'^2(t)}{h(t)} + F(v_a(t)) \leq F(v_a(M_a)). \quad (2.37)$$

Rewriting and integrating (2.37) on $(0, M_a)$ gives

$$\begin{aligned} \int_0^{M_a} \frac{v_a'(t) dt}{\sqrt{2} \sqrt{F(v_a(M_a)) - F(v_a(t))}} &\leq \int_0^{M_a} \sqrt{h(t)} dt \\ &\leq \sqrt{h_2} \int_0^{R^{2-N}} t^{-\tilde{\alpha}/2} dt \\ &= \frac{2\sqrt{h_2}}{2 - \tilde{\alpha}} (R^{2-N})^{1 - \frac{\tilde{\alpha}}{2}}. \end{aligned} \quad (2.38)$$

Since $v_a(M_a) \rightarrow \infty$ as $a \rightarrow \infty$ from (2.36) it follows from (H3) that $F(v_a(M_a)) - F(s) \leq C_{10} v_a^{p+1}(M_a)$ for some constant $C_{10} > 0$. Then after changing variables on the left-hand side of (2.38) and rewriting we obtain

$$\begin{aligned} \frac{v_a^{\frac{1-p}{2}}(M_a)}{\sqrt{2C_{10}}} &= \frac{v_a(M_a)}{\sqrt{2} \sqrt{C_{10} v_a^{p+1}(M_a)}} \\ &\leq \int_0^{v_a(M_a)} \frac{ds}{\sqrt{2} \sqrt{F(v_a(M_a)) - F(s)}} \\ &= \frac{2\sqrt{h_2}}{2 - \tilde{\alpha}} (R^{2-N})^{1 - \frac{\tilde{\alpha}}{2}}. \end{aligned} \quad (2.39)$$

This yields a contradiction since the right-hand side of (2.39) is finite but $0 < p < 1$ and by (2.36) the left-hand side of (2.39) goes to infinity as $a \rightarrow \infty$. Thus the assumption that v_a has a local maximum on $[0, R^{2-N}]$ if a is sufficiently large is false. Therefore if a is sufficiently large then v_a is increasing on $[0, R^{2-N}]$ and

so $v_a(R^{2-N}) = \max_{[0, R^{2-N}]} v_a(t)$. Since from the first part of the proof we know that $\lim_{a \rightarrow \infty} \max_{[0, R^{2-N}]} v_a(t) = \infty$ it follows that $\lim_{a \rightarrow \infty} v_a(R^{2-N}) = \infty$. This completes the proof. \square

Lemma 2.4. *Let $v_a(t)$ satisfy (2.4), (2.8) and assume (H1)–(H6) hold. Let $R > 0$ be sufficiently small. Then $v_a(t)$ has a local maximum, M_a , and a zero, Z_a , with $0 < M_a < Z_a < R^{2-N}$ if a is sufficiently small. In addition, if $R > 0$ is sufficiently small then v_a has n zeros on $[0, R^{2-N}]$.*

Proof. Let us suppose instead that $v'_a(t) > 0$ on $[0, R^{2-N}]$ for all sufficiently small a and R sufficiently small. Then from (2.18) it follows that $t_{a,\gamma} \leq C_{11}$ where C_{11} is independent of a . Thus $t_{a,\gamma} < R^{2-N}$ if R is sufficiently small. Since v_a is continuous and increasing then for $t > t_{a,\gamma}$ we have $\gamma = v_a(t_{a,\gamma}) < v_a(t)$. Since $v'_a(t) > 0$ and $f(v_a) > 0$ on $[\gamma, \infty)$ with $f(v_a) \rightarrow \infty$ as $v_a \rightarrow \infty$ by (H3) it follows that there exists $C_{12} > 0$ such that $f(v_a) \geq C_{12} > 0$ on $[t_{a,\gamma}, R^{2-N}]$. Then

$$v''_a(t) + C_{12}h(t) \leq v''_a(t) + h(t)f(v_a(t)) = 0 \quad \text{on } [t_{a,\gamma}, R^{2-N}]. \quad (2.40)$$

Rewriting and integrating on $(t_{a,\gamma}, t)$ gives

$$0 < v'_a(t) \leq v'_a(t_{a,\gamma}) - C_{12} \left[\frac{t^{1-\tilde{\alpha}} - t_{a,\gamma}^{1-\tilde{\alpha}}}{1-\tilde{\alpha}} \right]. \quad (2.41)$$

From (2.6) we know $0 < \tilde{\alpha} < 1$ and it follows from (2.26) that if $0 \leq a \leq a_0$ then

$$|v'_a(t)| \leq a + C_7 \leq a_0 + C_7. \quad (2.42)$$

Thus $v'_a(t_{a,\gamma})$ is bounded by a constant that is independent of a when a is sufficiently small and so it follows that the right-hand side of (2.41) becomes negative if R is sufficiently small which contradicts the assumption that $v'_a(t) > 0$ on $[0, R^{2-N}]$. Thus if a is sufficiently small and R is sufficiently small then there is an M_a with $0 < M_a < R^{2-N}$ such that $v'_a > 0$ on $(0, M_a)$ and $v'_a(M_a) = 0$.

Next, we want to show that v_a has a zero on $[0, R^{2-N}]$ if a and R are sufficiently small. In order to do this we will show that $v_a \rightarrow v_0$ uniformly on $[0, R^{2-N}]$ as $a \rightarrow 0^+$ where

$$\begin{aligned} v''_0 + h(t)f(v_0) &= 0, \\ v_0(0) = 0 &= v'_0(0). \end{aligned}$$

Then we will show v_0 has a zero and since $v_a \rightarrow v_0$ uniformly as $a \rightarrow 0^+$ it will follow that v_a has a zero if a is sufficiently small and R is sufficiently small.

It follows from Lemmas 2.1 and 2.2, and (2.28)–(2.29) that v_a, v'_a are uniformly bounded on $[0, R^{2-N}]$ for all $0 \leq a \leq a_0$ for some $a_0 > 0$. Therefore there is a subsequence of the v_a , say v_{a_j} , such that $v_{a_j} \rightarrow v_0$ uniformly on $[0, R^{2-N}]$ by the Arzela-Ascoli Theorem as $a_j \rightarrow 0$.

Now we assume there is a $t_{a,\beta}$ with $0 < t_{a,\beta} < R^{2-N}$ such that $v_a(t_{a,\beta}) = \beta$ and $0 \leq v_a(t) < \alpha$ on $[0, t_{a,\beta})$. It follows from (2.21) and an argument similar to (2.22) that

$$\beta \leq t_{a,\beta}(a + C_5) \quad (2.43)$$

and as in (2.19) we have

$$0 \leq v''_a \leq \frac{h_2}{C_1^q} t^{\frac{-\tilde{\alpha}-2q}{1+q}} + h_2 L_1 \beta t^{-\tilde{\alpha}} \leq C_{13} t^{\frac{-\tilde{\alpha}-2q}{1+q}} \quad \text{on } [0, t_{a,\beta}] \quad (2.44)$$

where $C_{13} = \frac{h_2}{C_1^q} + h_2 L_1 \beta R^{\frac{(2-N)(2-\tilde{\alpha})q}{1+q}}$.

Thus for $0 < x < y < t_{a,\beta}$ and since $0 < \frac{1-\bar{\alpha}-q}{1+q} < 1$ we have

$$\begin{aligned} 0 \leq v'_a(y) - v'_a(x) &= \int_x^y v''_a(t) dt \\ &\leq C_{13} \int_x^y t^{-\frac{\bar{\alpha}-2q}{1+q}} dt \\ &= C_{14} |y^{\frac{1-\bar{\alpha}-q}{1+q}} - x^{\frac{1-\bar{\alpha}-q}{1+q}}| \\ &\leq C_{14} |y - x|^{\frac{1-\bar{\alpha}-q}{1+q}} \end{aligned} \tag{2.45}$$

where $C_{14} = \frac{1+q}{1-\bar{\alpha}-q} C_{13}$. And since $0 < \frac{\beta}{a_0+C_5} \leq t_{a,\beta}$ from (2.43) it follows from this that the v'_a are equicontinuous on $[0, \frac{\beta}{a_0+C_5}]$ for $0 \leq a \leq a_0$ and so $v'_{a_j} \rightarrow v'_0$ uniformly on $[0, \frac{\beta}{a_0+C_5}]$ by the Arzela-Ascoli Theorem.

Now if $0 < v_a < \beta$ on $[0, R^{2-N}]$ then we see (2.44) and (2.45) hold $[0, R^{2-N}]$. Next we choose t_0 with $0 < t_0 < \frac{\beta}{a_0+C_5}$. Then integrating (2.13) on (t_0, t) gives:

$$\frac{1}{2}v'^2_{a_j}(t) + h(t)F(v_{a_j}(t)) = \frac{1}{2}v'^2_{a_j}(t_0) + \int_{t_0}^t h'(s)F(v_{a_j}(s)) ds. \tag{2.46}$$

Now since $v_{a_j} \rightarrow v_0$ uniformly and since $v'_{a_j}(t_0) \rightarrow v'_0(t_0)$ it then follows that $v'_{a_j} \rightarrow v'_0$ uniformly on $[t_0, R^{2-N}]$, and so combined with the earlier fact $v'_{a_j} \rightarrow v'_0$ uniformly on $[0, \frac{\beta}{a_0+C_5}]$ we see that $v'_{a_j} \rightarrow v'_0$ uniformly on $[0, R^{2-N}]$.

Now taking limits in (2.46) gives

$$\frac{1}{2}v'^2_0(t) + h(t)F(v_0(t)) = \frac{1}{2}v'^2_0(t_0) + \int_{t_0}^t h'(s)F(v_0(s)) ds \text{ on } (0, R^{2-N}].$$

Letting $t_0 \rightarrow 0^+$ gives

$$\frac{1}{2}v'^2_0(t) + h(t)F(v_0(t)) = \int_0^t h'(s)F(v_0(s)) ds.$$

Then from (2.4) and (H3) we see that $v''_{a_j} \rightarrow v''_0$ at all points where $v_0(t) \neq 0$ and at these points we have

$$\begin{aligned} v''_0 + h(t)f(v_0) &= 0, \\ v_0(0) = v'_0(0) &= 0. \end{aligned}$$

As at the beginning of the proof of this lemma it follows that v_0 has a local maximum, M_0 , and $v_0(M_0) > \gamma$ if $R > 0$ is sufficiently small. Now we assume by way of contradiction $v_0 > \gamma$ on $[M_0, R^{2-N}]$. Then we have $\frac{f(v_0)}{v_0} > 0$ on $[M_0, R^{2-N}]$ so there is a $C_{15} > 0$ such that $\frac{f(v_0)}{v_0} \geq C_{15} > 0$ when $\gamma \leq v_0 \leq v_0(M_0)$. Thus substituting in (2.4) and using (2.7) we obtain

$$v''_0(t) + \frac{h_0 C_{15}}{t^{\bar{\alpha}}} v_0(t) \leq 0.$$

So $v''_0 < 0$ while $\gamma \leq v_0 \leq v_0(M_0)$. Integrating $v''_0 < 0$ twice on $(M_0 + \epsilon, t)$ we have

$$v_0(t) \leq v_0(M_0 + \epsilon) + v'_0(M_0 + \epsilon)(t - (M_0 + \epsilon)). \tag{2.47}$$

Now if R is sufficiently small then R^{2-N} will be very large and thus we may choose t sufficiently large so that the right-hand side of (2.47) becomes negative

contradicting that $v_0 \geq \gamma$. So there exists $t_{\gamma_0} > M_0$ such that $v_0(t_{\gamma_0}) = \gamma$ and $v'_0 < 0$ on (M_0, t_{γ_0}) if R is sufficiently small.

Next while $\beta < \frac{\gamma+\beta}{2} \leq v_0 \leq \gamma$ then $f(v_0) > 0$ so $v''_0 < 0$. Integrating $v''_0 < 0$ twice on (t_{γ_0}, t) gives

$$v_0(t) < \gamma + v'_0(t_{\gamma_0})(t - t_{\gamma_0}) \quad \text{with } v'_0(t_{\gamma_0}) < 0.$$

Now again if R is sufficiently small then R^{2-N} is very large and so we can choose t sufficiently large from which it would follow that $v_0(t) < \frac{\gamma+\beta}{2}$ contradicting that $v_0(t) \geq \frac{\gamma+\beta}{2}$. So there is a $t_{\gamma_1} > t_{\gamma_0}$ such that $v_0(t_{\gamma_1}) = \frac{\gamma+\beta}{2}$.

Now assume $v_0(t) > 0$ on (M_0, R^{2-N}) . Then recall that $\frac{1}{2} \frac{v_0'^2}{h(t)} + F(v_0) > 0$ and there exists $C_{16} > 0$ so $-F(v_0) \geq C_{16}v_0^{1-q}$ for $t > t_{\gamma_1}$. Therefore,

$$-\frac{v'_0}{v_0^{\frac{1+q}{2}}} \geq \sqrt{2C_{16}h_0} t^{-\tilde{\alpha}/2} \quad \text{on } (t_{\gamma_1}, t).$$

Integrating on (t_{γ_1}, t) gives

$$0 < v_0^{\frac{1+q}{2}}(t) \leq \left(\frac{\gamma + \beta}{2}\right)^{\frac{1+q}{2}} - \frac{(1+q)\sqrt{2C_{16}h_0}}{2-\tilde{\alpha}} \left[t^{\frac{2-\tilde{\alpha}}{2}} - t_{\gamma_1}^{\frac{2-\tilde{\alpha}}{2}}\right]. \tag{2.48}$$

And again if R is sufficiently small then we can choose t sufficiently large so that the right-hand side of (2.48) becomes negative contradicting that $v_0 > 0$. Thus v_0 has a first positive zero, Z_1 , on $[0, R^{2-N}]$ if $R > 0$ is sufficiently small. Also $0 < \frac{1}{2} \frac{v_0'^2}{h(t)} + F(v_0)$ for $t > 0$ so $0 < \frac{1}{2} \frac{v_0'^2(Z_1)}{h(Z_1)}$ and therefore $v'_0(Z_1) < 0$. Thus $v_0(Z_1 + \epsilon) < 0$ for $\epsilon > 0$ sufficiently small. Then since $v_a \rightarrow v_0$ uniformly on $[0, Z_1 + \epsilon]$ it follows that $v_a(Z_1 + \epsilon) < 0$ if a is sufficiently small and therefore if $a > 0$ and R are sufficiently small we see that v_a has a zero $0 < Z_{1,a} < R^{2-N}$. Then as at the beginning of the proof where we showed that v_a has a local maximum, a similar argument shows v_a has a local minimum, m_a , with $Z_{1,a} < m_a$ and then v_a has a second zero, $Z_{2,a}$, with $Z_{2,a} > m_a$, if $a > 0$ and R are sufficiently small. Continuing in this way we can find n zeros on $[0, R^{2-N}]$ if R is small enough. This completes the proof. \square

3. PROOF OF MAIN RESULTS

Proof of Theorem 1.1. Consider the set

$$S_0 = \{a > 0 : v_a(t) > 0 \text{ on } (0, R^{2-N})\}.$$

If a is sufficiently large then $v_a(t) > 0$ on $(0, R^{2-N})$ by Lemma 2.3 and therefore $v_a \in S_0$ if a is sufficiently large. Thus $S_0 \neq \emptyset$. Also if a and R are sufficiently small then v_a has a zero on $(0, R^{2-N})$ by Lemma 2.4. Thus S_0 is bounded from below by a positive constant if R is sufficiently small. Now let

$$a_0 = \inf S_0.$$

We now show that $v_{a_0} > 0$ on $(0, R^{2-N})$ and $v_{a_0}(R^{2-N}) = 0$. Suppose on the contrary that there exists a zero, $Z_{a_0} \in (0, R^{2-N})$, and $v_{a_0} > 0$ on $(0, Z_{a_0})$ with $v_{a_0}(Z_{a_0}) = 0$. Then $0 < E_a(Z_{a_0}) = \frac{1}{2} \frac{v_{a_0}'^2(Z_{a_0})}{h(Z_{a_0})}$ so $v'_{a_0}(Z_{a_0}) < 0$.

Thus for $Z_{a_0} < t_1 < R^{2-N}$ and t_1 close to Z_{a_0} we have $v_{a_0}(t_1) < 0$. Then for a close to a_0 with $a < a_0$ then $v_a(t_1) < 0$ by continuous dependence (Lemma

2.2) but this contradicts the definition of a_0 . Thus $v_{a_0} > 0$ on $(0, R^{2-N})$ and so $v_{a_0}(R^{2-N}) \geq 0$.

Next suppose that $v_{a_0}(R^{2-N}) > 0$. Then $v_{a_0} > 0$ on $(0, R^{2-N}]$ and for a close to a_0 with $a < a_0$ then $v_a > 0$ on $(0, R^{2-N}]$. But since $a < a_0$, it follows that $a \notin S_0$ so v_a must have a zero on $(0, R^{2-N}]$ which contradicts that $v_a > 0$ on $(0, R^{2-N}]$. Thus $v_{a_0}(R^{2-N}) = 0$. Also since E_a non-decreasing it follows that $0 < E_a(R^{2-N}) = \frac{1}{2} \frac{v_{a_0}^2(R^{2-N})}{h(R^{2-N})}$ so $v'_{a_0}(R^{2-N}) < 0$.

Next let us define

$$S_1 = \{a > 0 : v_a(t) \text{ solves (2.4), (2.8) and has exactly one zero on } (0, R^{2-N})\}.$$

If we choose a slightly smaller than a_0 and R sufficiently small then it follows from Lemma 2.4 that v_a has at least one zero, Z_{a_1} , on $(0, R^{2-N})$ and Z_{a_1} is close to R^{2-N} . Also we know $v'_{a_0}(R^{2-N}) < 0$ so if a is sufficiently close to a_0 then $v'_a < 0$ on (Z_{a_1}, R^{2-N}) . Thus v_a has at most one zero on $(0, R^{2-N})$ if a is sufficiently close to a_0 . Therefore S_1 is nonempty. We also know from Lemma 2.4 that if R is sufficiently small then v_a has a second zero on $(0, R^{2-N})$. Therefore S_1 is bounded from below. So let

$$a_1 = \inf S_1.$$

In a similar way we can show that v_{a_1} has exactly one zero on $(0, R^{2-N})$ and $v_{a_1}(R^{2-N}) = 0$. In a similar fashion we can show that if n_0 is a given nonnegative integer then if $R > 0$ is sufficiently small then there exists a_0, a_1, \dots, a_{n_0} such that v_{a_k} has k zeros on $(0, R^{2-N})$ and $v_{a_k}(R^{2-N}) = 0$. Finally, let $u_k(r) = v_{a_k}(r^{2-N})$. Then $u_k(r)$ satisfies (1.1)–(1.3) and u_k has k zeros on (R, ∞) . This completes the proof. \square

Proof of Theorem 1.2. Suppose there is a solution, v_a , of (2.4) with $v_a(0) = v_a(R^{2-N}) = 0$. This then implies that v_a has a local maximum, M_a , with $0 < M_a < R^{2-N}$ and $v'_a(M_a) = 0$. Since E_a is non-decreasing (by (2.10)) then for $0 < t < M_a$,

$$0 < \frac{1}{2} \frac{v_a^2}{h(t)} + F(v_a(t)) = E_a(t) \leq E_a(M_a) = F(v_a(M_a)). \tag{3.1}$$

Thus $v_a(M_a) > \gamma$. Rewriting and integrating (3.1) on $(0, M_a)$ gives

$$\begin{aligned} \int_0^{M_a} \frac{v'_a(t) dt}{\sqrt{2}\sqrt{F(v_a(M_a)) - F(v_a(t))}} &\leq \int_0^{M_a} \sqrt{h_2} t^{-\tilde{\alpha}/2} dt \\ &= \frac{2\sqrt{h_2}}{2 - \tilde{\alpha}} M_a^{\frac{2-\tilde{\alpha}}{2}} \\ &\leq \frac{2\sqrt{h_2}}{2 - \tilde{\alpha}} (R^{2-N})^{\frac{2-\tilde{\alpha}}{2}}. \end{aligned} \tag{3.2}$$

Since $\tilde{\alpha} < 1$ and from (H4) we have $-F(v_a(t)) \leq F_0$ so it follows that $F(v_a(M_a)) - F(v_a(t)) \leq F(v_a(M_a)) + F_0$ which we apply to (3.2) to obtain

$$\int_0^{M_a} \frac{v'_a(t) dt}{\sqrt{2}\sqrt{F(v_a(M_a)) - F(v_a(t))}} \geq \frac{v_a(M_a)}{\sqrt{2}\sqrt{F(v_a(M_a)) + F_0}}. \tag{3.3}$$

Next from (H3) it follows that there is a constant $F_1 > 0$ such that $F(x) \leq F_1|x|^{p+1}$ for all x and therefore it follows from (3.2)-(3.3) and that $v_a(M_a) > \gamma$ that

$$\frac{\gamma^{\frac{1-p}{2}}}{\sqrt{2}\sqrt{F_1 + \frac{F_0}{\gamma^{p+1}}}} \leq \frac{v_a^{\frac{1-p}{2}}(M_a)}{\sqrt{2}\sqrt{F_1 + \frac{F_0}{v_a^{p+1}(M_a)}}} \leq \frac{2\sqrt{h_2}}{2 - \tilde{\alpha}} (R^{2-N})^{\frac{2-\tilde{\alpha}}{2}}. \tag{3.4}$$

Thus the right-hand side of (3.4) goes to zero if R sufficiently large but the left-hand side of (3.4) is positive and independent of R . Thus (1.1)–(1.3) has no solutions if R is sufficiently large. This completes the proof. \square

4. APPENDIX

Lemma 4.1. *Let $a > 0$ and (H1)–(H6) hold. Then there exists a solution v_a of (2.4), (2.8) on $(0, \epsilon]$ for some $\epsilon > 0$.*

Proof. This is similar to the proof of existence in [1] which we include here for completeness. First integrate (2.4) over $(0, t)$ and use (2.8). This gives

$$v'_a(t) = a - \int_0^t h(s)f(v_a(s)) ds \quad \text{for } t > 0. \tag{4.1}$$

Integrate again over $(0, t)$ and using (2.8) gives

$$v_a(t) = at - \int_0^t \int_0^s h(x)f(v_a(x)) dx ds \quad \text{for } t > 0. \tag{4.2}$$

Now let $W(t) = \frac{v_a(t)}{t}$ so $v_a(t) = tW(t)$ and $W(0) = \lim_{t \rightarrow 0^+} \frac{v_a(t)}{t} = v'_a(0) = a$. Rewriting (4.2) we obtain

$$W(t) = a - \frac{1}{t} \int_0^t \int_0^s h(x)f(xW(x)) dx ds \quad \text{for } t > 0. \tag{4.3}$$

We now we solve equation (4.3) on $(0, \epsilon]$ by a fixed point method as follows. Let us define

$$S = \left\{ W : [0, \epsilon] \rightarrow \mathbb{R} \text{ with } W(0) = a > 0, W \in C[0, \epsilon] \text{ and } |W(t) - a| \leq \frac{a}{2} \text{ on } [0, \epsilon] \right\} \tag{4.4}$$

where $C[0, \epsilon]$ is the set of continuous functions on $[0, \epsilon]$ and $\epsilon > 0$. Let

$$\|W\| = \sup_{x \in [0, \epsilon]} |W(x)|.$$

Then $(S, \|\cdot\|)$ is a Banach space. Let us define a map T on S by

$$TW(t) = \begin{cases} a & \text{for } t = 0 \\ a - \frac{1}{t} \int_0^t \int_0^s h(x)f(xW(x)) dx ds & \text{for } 0 < t \leq \epsilon. \end{cases}$$

From (4.4) we see $0 < \frac{a}{2} \leq W(x) \leq \frac{3a}{2}$ on $[0, \epsilon]$ so it follows that $|\frac{-1}{x^q W^q(x)}| \leq \frac{2^q x^{-q}}{a^q}$ on $(0, \epsilon]$ and since we know from (H1)–(H2) that $g_1(x)$ is locally Lipschitz this then implies that there exists $L_1 > 0$ such that

$$|g_1(x)| \leq L_1|x| \quad \text{on } [0, \gamma]. \tag{4.5}$$

Now let $W \in S$ and suppose $0 < \epsilon < \frac{2\gamma}{3a}$. Then on $[0, \epsilon]$ we have

$$0 \leq xW(x) < \epsilon \frac{3a}{2} < \frac{2\gamma}{3a} \frac{3a}{2} = \gamma.$$

using (H2), (2.6), and (4.5) we estimate

$$|h(x)f(xW(x))| = \left| h(x) \left(\frac{-1}{x^q W^q(x)} + g_1(xW(x)) \right) \right| \leq \frac{h_2 2^q}{a^q} x^{-(\tilde{\alpha}+q)} + \frac{3ah_2 L_1}{2} x^{1-\tilde{\alpha}}.$$

Recalling from (2.6) that $\tilde{\alpha} + q < 1$ then integrating once over $[0, t]$ gives

$$\int_0^t |h(x)f(xW(x))| dx \leq \frac{A_1}{a^q} t^{1-\tilde{\alpha}-q} + A_2 a t^{2-\tilde{\alpha}} \tag{4.6}$$

where $A_1 = \frac{h_2 2^q}{(1-\tilde{\alpha}-q)}$ and $A_2 = \frac{3h_2 L_1}{2(2-\tilde{\alpha})}$. Thus from (4.6) we have

$$\lim_{t \rightarrow 0^+} \int_0^t |h(x)f(xW(x))| dx = 0. \tag{4.7}$$

Integrating (4.6) again gives

$$\int_0^t \int_0^s |h(x)f(xW(x))| dx ds \leq \frac{A_3 t^{2-\tilde{\alpha}-q}}{a^q} + a A_4 t^{3-\tilde{\alpha}} \tag{4.8}$$

where $A_3 = \frac{h_2 2^q}{(2-\tilde{\alpha}-q)(1-\tilde{\alpha}-q)}$ and $A_4 = \frac{3h_2 L_1}{2(2-\tilde{\alpha})(3-\tilde{\alpha})}$. So we see

$$\lim_{t \rightarrow 0^+} \int_0^t \int_0^s |h(x)f(xW(x))| dx ds = 0. \tag{4.9}$$

We now show that $T(W) \in S$ for each $W \in S$ if $\epsilon > 0$ is sufficiently small so we first let $W \in S$. It follows then from (4.9) that $T(W)$ is continuous on $[0, \epsilon]$. Thus we see $\lim_{t \rightarrow 0^+} TW(t) = a$ and so $|TW(t) - a| \leq \frac{a}{2}$ on $[0, \epsilon]$ if $\epsilon > 0$ is sufficiently small. Therefore $T : S \rightarrow S$ if ϵ is sufficiently small.

We next prove that T is a contraction mapping if ϵ is sufficiently small. Let $W_1, W_2 \in S$ and suppose $0 < \epsilon < \frac{2\gamma}{3a}$. Then

$$TW_1(t) - TW_2(t) = -\frac{1}{t} \int_0^t \int_0^s h(x)[f(xW_1(x)) - f(xW_2(x))] dx ds. \tag{4.10}$$

By (H2) we have $f(xW(x)) = -x^{-q}W^{-q}(x) + g_1(xW(x))$ where $0 < q < 1$. Then as earlier before (4.5) we see that $0 \leq xW_i \leq \epsilon \frac{3a}{2} < \gamma$ on $[0, \epsilon]$ for $i = 1, 2$ therefore using (4.5) this gives

$$\begin{aligned} |f(xW_1(x)) - f(xW_2(x))| &= \left| \frac{-1}{x^q} \left[\frac{1}{W_1^q} - \frac{1}{W_2^q} \right] + g_1(xW_1(x)) - g_1(xW_2(x)) \right| \\ &\leq \frac{1}{x^q} \left| \frac{1}{W_1^q} - \frac{1}{W_2^q} \right| + L_1 x |W_1 - W_2|. \end{aligned} \tag{4.11}$$

Next applying the mean value theorem we see that the right-hand side of (4.11) is bounded by

$$\frac{1}{x^q} \left[\frac{q}{W_3^{q+1}} |W_1 - W_2| \right] + L_1 x |W_1 - W_2|$$

where W_3 is between W_1 and W_2 . Since $W_i \in S$ for $i = 1, 2, 3$ and $|W_i - a| \leq \frac{a}{2}$ then $\frac{a}{2} \leq W_i \leq \frac{3a}{2}$ on $[0, \epsilon]$. Therefore it follows that $W_3^{q+1} \geq \left(\frac{a}{2}\right)^{q+1}$ and so we have

$$|f(xW_1(x)) - f(xW_2(x))| \leq |W_1 - W_2| \left[\frac{q}{x^q} \left(\frac{2}{a}\right)^{q+1} + L_1 x \right] \quad \text{on } (0, \epsilon]. \tag{4.12}$$

Recalling that $|h(t)| \leq \frac{h_2}{t^{\tilde{\alpha}}}$ and $\tilde{\alpha} + q < 1$ from (2.6), and $t \in (0, \epsilon]$, then using (4.12) in (4.10) gives

$$\begin{aligned} |TW_1 - TW_2| &\leq \frac{1}{t} \int_0^t \int_0^s \frac{h_2}{x^{\tilde{\alpha}}} |W_1 - W_2| \left[\frac{q}{x^q} \left(\frac{2}{a}\right)^{q+1} + L_1 x \right] dx ds \\ &\leq \frac{1}{t} \|W_1 - W_2\| \int_0^t \int_0^s \frac{h_2}{x^{\tilde{\alpha}}} \left[\frac{q}{x^q} \left(\frac{2}{a}\right)^{q+1} + L_1 x \right] dx ds \\ &\leq \|W_1 - W_2\| \left[\frac{A_5 \epsilon^{1-q-\tilde{\alpha}}}{a^{q+1}} + A_6 \epsilon^{2-\tilde{\alpha}} \right], \end{aligned}$$

where $A_5 = \frac{h_2 q 2^{q+1}}{(2-q-\tilde{\alpha})(1-q-\tilde{\alpha})}$ and $A_6 = \frac{h_2 L_1}{(3-\tilde{\alpha})(2-\tilde{\alpha})}$. Since

$$\lim_{\epsilon \rightarrow 0^+} \left[\frac{A_5 \epsilon^{1-q-\tilde{\alpha}}}{a^{q+1}} + A_6 \epsilon^{2-\tilde{\alpha}} \right] = 0,$$

for $\epsilon > 0$ sufficiently small we see that

$$|TW_1 - TW_2| \leq c \|W_1 - W_2\|,$$

where

$$c = \frac{A_5 \epsilon^{1-q-\tilde{\alpha}}}{a^{q+1}} + A_6 \epsilon^{2-\tilde{\alpha}}. \tag{4.13}$$

Thus for ϵ sufficiently small we see $0 < c < 1$ and therefore T is a contraction mapping on S .

Thus by the contraction mapping principle [5] there exists a unique solution $W \in S$ to $TW = W$ on $[0, \epsilon]$ for some $\epsilon > 0$. And then $v_a(t) = tW(t)$ is a solution of (2.4) on $(0, \epsilon]$ for some $\epsilon > 0$. This completes the proof. \square

Lemma 4.2. *Let $a = 0$ and (H1)–(H6) hold. Then there exists a solution $v_0 > 0$ of equation (2.4) with $v_0(0) = v'_0(0) = 0$ on $(0, \epsilon]$ for some $\epsilon > 0$.*

Proof. Suppose first that v_0 is a solution to (2.4) on $(0, \epsilon]$ with

$$v_0(0) = 0, \quad v'_0(0) = 0. \tag{4.14}$$

Let us determine the behavior of $v_0(t)$ on $(0, \epsilon)$. using the fact that $f(v_a) = \frac{-1}{|v_a|^{q-1} v_a} + g_1(v_a)$ where $0 < q < 1$, $g_1(0) = 0$, and g_1 is continuous at 0, then integrating (2.4) on $(0, t)$ and using $v'_0(0) = 0$ gives:

$$v'_0(t) = - \int_0^t h(s) f(v_0(s)) ds.$$

Integrating again on $(0, t)$ and using $v_0(0) = 0$ gives

$$v_0(t) = - \int_0^t \int_0^s h(x) f(v_0(x)) dx ds. \tag{4.15}$$

Now let $v_0(t) = t^{\frac{2-\tilde{\alpha}}{1+q}} W(t)$ where $W(0) \neq 0$. Rewriting (4.15) we have

$$W(t) = \frac{1}{t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[\frac{1}{x^{\frac{(2-\tilde{\alpha})q}{1+q}}} W^q(x) - g\left(x^{\frac{2-\tilde{\alpha}}{1+q}} W(x)\right) \right] dx ds. \tag{4.16}$$

Assuming $W(t)$ is continuous at 0, taking the limit of (4.16) and using L'Hôpital's rule twice gives

$$\begin{aligned}
 W(0) &= \lim_{t \rightarrow 0^+} W(t) \\
 &= A_7 \lim_{t \rightarrow 0^+} \frac{t^{\tilde{\alpha}} h(t) \left[\frac{t^{-\tilde{\alpha}}}{t^{\frac{(2-\tilde{\alpha})q}{1+q}} W^q(t)} \right] - g_1 \left(t^{\frac{2-\tilde{\alpha}}{1+q}} W(t) \right) h(t)}{t^{\frac{-\tilde{\alpha}-2q}{1+q}}} \\
 &= A_7 \left[\lim_{t \rightarrow 0^+} \frac{t^{\tilde{\alpha}} h(t)}{W^q(t)} - \lim_{t \rightarrow 0^+} \frac{h(t) g_1 \left(t^{\frac{2-\tilde{\alpha}}{1+q}} W(t) \right)}{t^{\frac{-\tilde{\alpha}-2q}{1+q}}} \right] \\
 &= \frac{A_7 h_1}{W^q(0)} - A_7 \lim_{t \rightarrow 0^+} \frac{h(t) g_1 \left(t^{\frac{2-\tilde{\alpha}}{1+q}} W(t) \right)}{t^{\frac{-\tilde{\alpha}-2q}{1+q}}},
 \end{aligned} \tag{4.17}$$

where $A_7 = \left(\frac{1+q}{2-\tilde{\alpha}}\right) \left(\frac{1+q}{1-\tilde{\alpha}-q}\right)$. Since $t^{\tilde{\alpha}} h(t) \rightarrow h_1 > 0$, by (2.6) as $t \rightarrow 0^+$, $0 < \tilde{\alpha} < 1$ and $|g_1(v)| \leq L_1|v|$ on $[0, \gamma]$ it follows that

$$\left| \frac{h(t) g_1 \left(t^{\frac{2-\tilde{\alpha}}{1+q}} W(t) \right)}{t^{\frac{-\tilde{\alpha}-2q}{1+q}}} \right| \leq \frac{h_2 t^{-\tilde{\alpha}} L_1 t^{\frac{2-\tilde{\alpha}}{1+q}}}{t^{\frac{-\tilde{\alpha}-2q}{1+q}}} |W(t)| = h_2 L_1 t^{2-\tilde{\alpha}} |W(t)| \rightarrow 0$$

as $t \rightarrow 0^+$. Then we have

$$W^{q+1}(0) = h_1 A_7 = \frac{h_1(1+q)^2}{(2-\tilde{\alpha})(1-\tilde{\alpha}-q)},$$

hence

$$W(0) = \left[\frac{h_1(1+q)^2}{(2-\tilde{\alpha})(1-\tilde{\alpha}-q)} \right]^{\frac{1}{q+1}} \equiv b_0. \tag{4.18}$$

Now let $W(t) = b_0 Y(t)$. Then $Y(0) = 1$ and (4.16) becomes

$$Y(t) = \frac{1}{t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[\frac{1}{x^{\frac{(2-\tilde{\alpha})q}{1+q}} b_0^{q+1} Y^q(x)} - \frac{g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y(x) \right)}{b_0} \right] dx ds. \tag{4.19}$$

Now we attempt to solve (4.19) by using the contraction mapping principle. Let us define

$$\begin{aligned}
 J = \left\{ Y \in C[0, \epsilon] : Y(0) = 1 \text{ and } |Y - 1| < \delta \text{ where} \right. \\
 \left. 0 < \delta < 1 \text{ is sufficiently small} \right\}.
 \end{aligned} \tag{4.20}$$

Let $\|Y\| = \sup_{x \in [0, \epsilon]} |Y(x)|$. Then $(J, \|\cdot\|)$ is a Banach space. Now we define T on J by

$$\begin{aligned}
 TY(t) &= \begin{cases} 1 & \text{for } t = 0 \\ \frac{1}{t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[\frac{1}{x^{\frac{(2-\tilde{\alpha})q}{1+q}} b_0^{q+1} Y^q(x)} - \frac{g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y(x) \right)}{b_0} \right] dx ds & \text{for } 0 < t \leq \epsilon. \end{cases}
 \end{aligned}$$

It is straightforward to show $TY(t)$ is continuous and from (4.18) and L'Hôpital's rule $\lim_{t \rightarrow 0^+} TY(t) = 1$. Thus it follows that $|TY(t) - 1| \leq \delta$ on $[0, \epsilon]$ if ϵ sufficiently small, and therefore $T : J \rightarrow J$ if ϵ and δ are sufficiently small.

Since $|Y - 1| < \delta < 1$ then $0 < 1 - \delta < Y < 1 + \delta$ and this implies that $\frac{1}{Y^q} \leq \frac{1}{(1-\delta)^q}$. Let us suppose $Y_1, Y_2 \in J$ then

$$\begin{aligned} & TY_1(t) - TY_2(t) \\ &= \frac{1}{t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[\frac{1}{x^{\frac{(2-\tilde{\alpha})q}{1+q}} b_0^{q+1}} \left(\frac{1}{Y_1^q(x)} - \frac{1}{Y_2^q(x)} \right) \right] dx ds \\ &\quad - \frac{1}{b_0 t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y_1(x) \right) + g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y_2(x) \right) \right] dx ds. \end{aligned} \quad (4.21)$$

For the integral in (4.21) since $Y_1, Y_2 \in J$, then by the mean value theorem there is a Y_3 between Y_1, Y_2 where $|Y_i - 1| < \delta$ for $i = 1, 2, 3$ (and therefore $1 - \delta < Y_3 < 1 + \delta$) then

$$\left| \frac{1}{Y_1^q} - \frac{1}{Y_2^q} \right| = \frac{q}{Y_3^{q+1}} |Y_1 - Y_2| \leq \frac{q}{(1-\delta)^{q+1}} |Y_1 - Y_2|.$$

Then using (2.6) the integral in (4.21) becomes

$$\begin{aligned} & \left| \frac{1}{t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[\frac{1}{x^{\frac{(2-\tilde{\alpha})q}{1+q}} b_0^{q+1}} \left(\frac{1}{Y_1^q} - \frac{1}{Y_2^q} \right) \right] dx ds \right| \\ & \leq \frac{q}{(1-\delta)^{1+q} b_0^{1+q}} \frac{|Y_1 - Y_2|}{t^{\frac{(2-\tilde{\alpha})q}{1+q}}} \int_0^t \int_0^s \frac{h(x)}{x^{\frac{(2-\tilde{\alpha})q}{1+q}}} dx ds \\ & \leq \frac{h_2 q}{(1-\delta)^{1+q} b_0^{1+q}} \frac{|Y_1 - Y_2|}{t^{\frac{(2-\tilde{\alpha})q}{1+q}}} \int_0^t \int_0^s x^{\frac{-(\tilde{\alpha}+2q)}{1+q}} dx ds \\ & \leq \frac{(1+q)^2 h_2 q}{(2-\tilde{\alpha})(1-\tilde{\alpha}-q)(1-\delta)^{1+q}} \frac{|Y_1 - Y_2|}{b_0^{1+q}} t^{\frac{(2-\tilde{\alpha})(1-q)}{1+q}}. \end{aligned}$$

Recalling $b_0^{q+1} = h_1 A_7 = h_1 \left(\frac{1+q}{2-\tilde{\alpha}} \right) \left(\frac{1+q}{1-\tilde{\alpha}-q} \right)$ we obtain the right-hand side of (4.21) is bounded by

$$\frac{h_2 q}{h_1 (1-\delta)^{1+q}} \epsilon^{\frac{(2-\tilde{\alpha})(1-q)}{1+q}} \|Y_1 - Y_2\|.$$

Since $\delta > 0$ and $0 < q < 1$ we see that for $\epsilon > 0$ sufficiently small,

$$\frac{h_2 q}{h_1 (1-\delta)^{1+q}} \epsilon^{\frac{(2-\tilde{\alpha})(1-q)}{1+q}} \leq d < 1.$$

For the integral in (4.21) since g_1 is locally Lipschitz at 0, it follows that

$$\left| g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y_1(x) \right) - g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y_2(x) \right) \right| \leq L_1 b_0 x^{\frac{2-\tilde{\alpha}}{1+q}} \|Y_1 - Y_2\|$$

so substituting this into (4.21) gives

$$\begin{aligned} & \left| \frac{-1}{b_0 t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s h(x) \left[g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y_1(x) \right) - g_1 \left(x^{\frac{2-\tilde{\alpha}}{1+q}} b_0 Y_2(x) \right) \right] dx ds \right| \\ & \leq \frac{|Y_1 - Y_2| h_2 L_1}{t^{\frac{2-\tilde{\alpha}}{1+q}}} \int_0^t \int_0^s x^{-\tilde{\alpha} + \frac{2-\tilde{\alpha}}{1+q}} dx ds \\ & \leq |Y_1 - Y_2| h_2 L_1 A_8 t^{\frac{2+q}{1+q}} \end{aligned} \quad (4.22)$$

where $A_8 = \left(\frac{1+q}{1+(2+q)(1-\tilde{\alpha})} \right) \left(\frac{1+q}{(2+q)(2-\tilde{\alpha})} \right)$. Since $\lim_{t \rightarrow 0^+} h_2 L_1 A_8 t^{\frac{2+q}{1+q}} = 0$ we can choose ϵ small enough so that $h_2 L_1 A_8 t^{\frac{2+q}{1+q}} < \frac{1-d}{2}$ and so combining (4.21) and

(4.22) we obtain

$$|TY_1(t) - TY_2(t)| \leq \frac{1+d}{2} \|Y_1 - Y_2\|$$

where $0 \leq d < 1$ and thus $\frac{1+d}{2} < 1$.

Thus T is a contraction mapping, so by the contraction mapping principle [5] there is a unique solution $Y \in J$ to $T(Y) = Y$ on $[0, \epsilon]$. Then $v_a(t) = t^{\frac{2-\alpha}{1+q}} W(t)$ is a solution of (2.4), (4.14) on $[0, \epsilon]$ for some $\epsilon > 0$. This completes the proof. \square

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